

Lecture slides (CT4201/EC4215 – Computer Graphics)

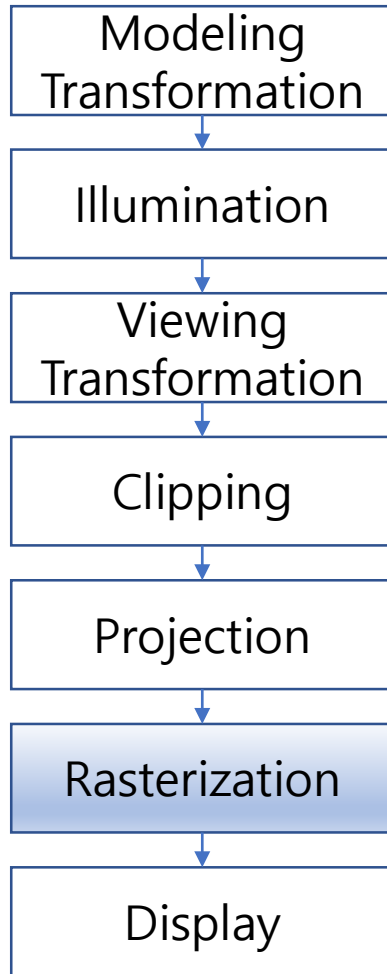
# Rasterization

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Lecturer: Bochang Moon

# Rasterization

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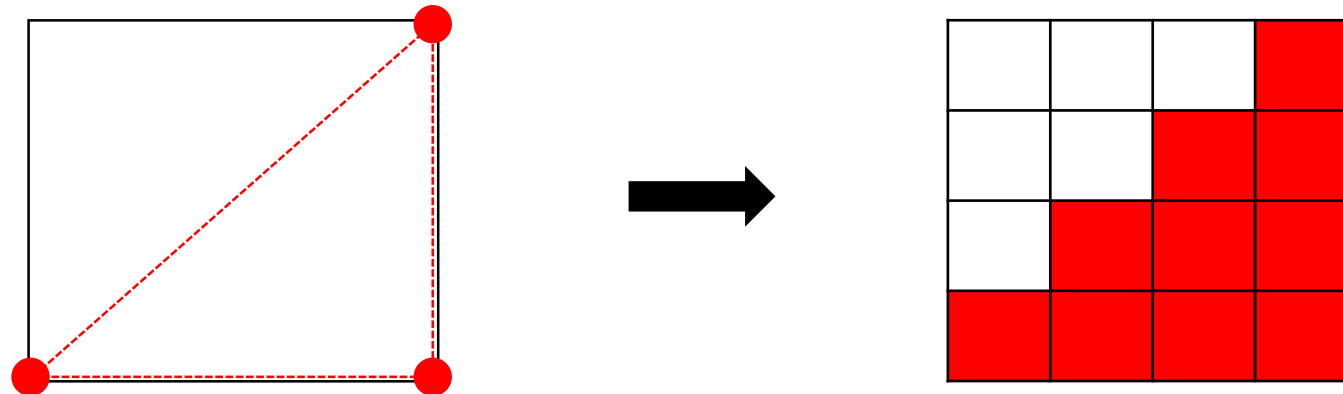


- Determine pixel values covered by primitives

# Triangle Rasterization

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- Draw a 2D triangles with 2D points  $p_0, p_1, p_2$  in screen coordinates
  - Each vertex can contain multiple properties
    - position, color, etc.
  - For intermediate pixels, we need interpolate them.



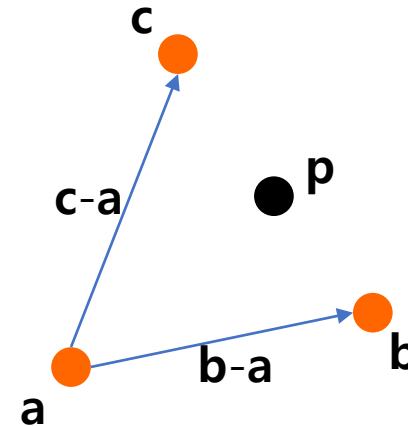
# Background: Barycentric Coordinates

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- Usually assign some properties (e.g., color) to each vertex in primitives and interpolate those values

- $\mathbf{p} = \mathbf{a} + \beta(\mathbf{b} - \mathbf{a}) + \gamma(\mathbf{c} - \mathbf{a})$
- $= (1 - \beta - \gamma)\mathbf{a} + \beta\mathbf{b} + \gamma\mathbf{c}$
- $= \alpha\mathbf{a} + \beta\mathbf{b} + \gamma\mathbf{c} \quad (\alpha \equiv 1 - \beta - \gamma)$

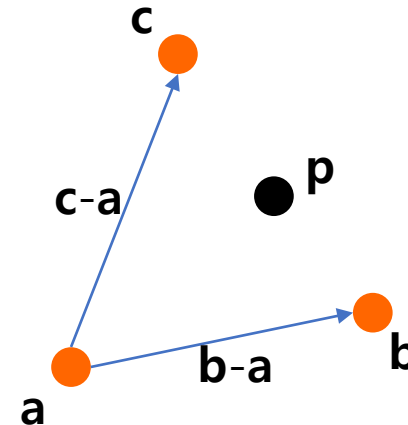
- $\mathbf{p}(\alpha, \beta, \gamma) = \alpha\mathbf{a} + \beta\mathbf{b} + \gamma\mathbf{c}$ 
  - with  $\alpha + \beta + \gamma = 1$



# Background: Barycentric Coordinates

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- $p(\alpha, \beta, \gamma) = \alpha a + \beta b + \gamma c$ 
  - with  $\alpha + \beta + \gamma = 1$
- Conditions for a point  $p$  inside the triangle
  - $0 < \alpha < 1$
  - $0 < \beta < 1$
  - $0 < \gamma < 1$
- Q. Conditions for a point on an edge?
- Q. Conditions for a point at a vertex?



# Background: Barycentric Coordinates

- $\mathbf{p}(\alpha, \beta, \gamma) = \alpha \mathbf{a} + \beta \mathbf{b} + \gamma \mathbf{c}$

- with  $\alpha + \beta + \gamma = 1$

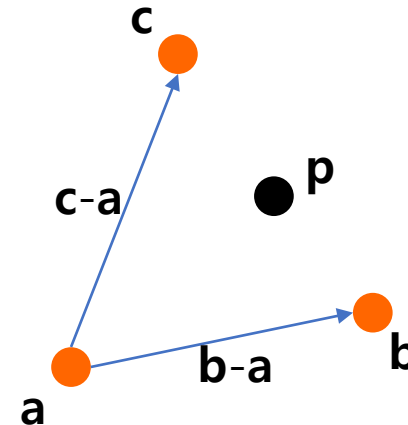
- Q. Given a point  $\mathbf{p}$ , how do we compute the coordinates?

- $\mathbf{p} = \mathbf{a} + \beta(\mathbf{b} - \mathbf{a}) + \gamma(\mathbf{c} - \mathbf{a})$

- Corresponding matrix form:

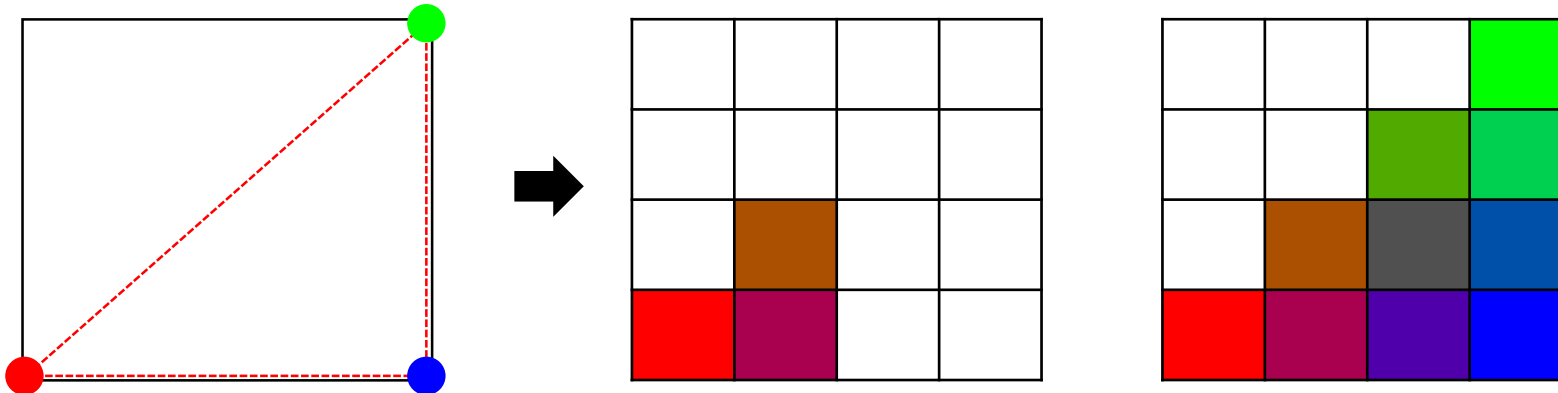
- $$\begin{bmatrix} x_b - x_a & x_c - x_a \\ y_b - y_a & y_c - y_a \end{bmatrix} \begin{bmatrix} \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} x_p - x_a \\ y_p - y_a \end{bmatrix}$$

- $\alpha = 1 - \beta - \gamma$



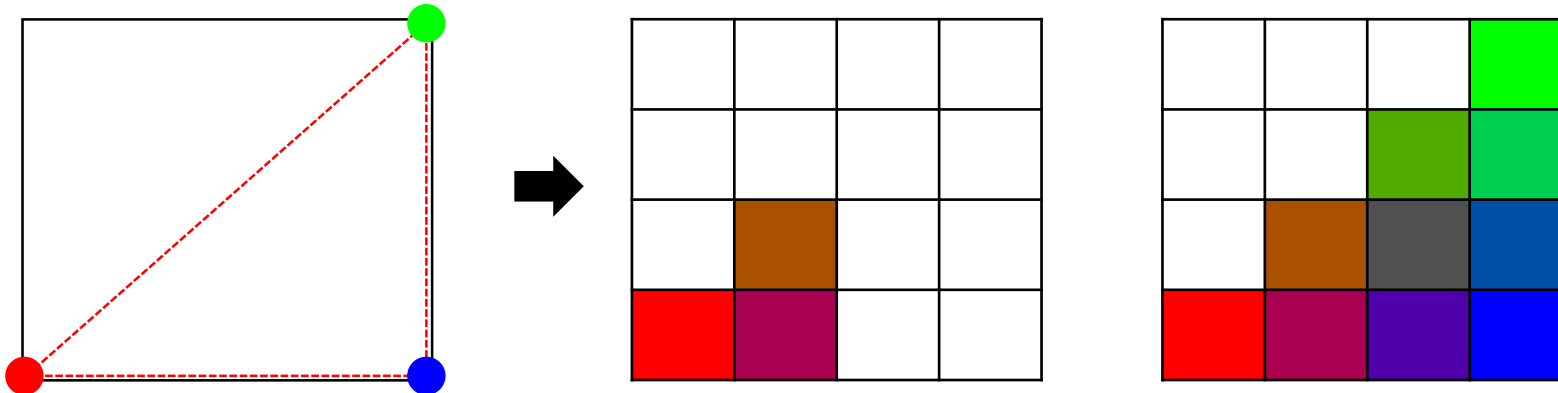
# Triangle Rasterization

- For all  $x$  do
  - For all  $y$  do
    - Compute  $\alpha, \beta, \gamma$  for  $(x, y)$
    - If  $(\alpha \in [0,1] \ \&\& \ \beta \in [0,1] \ \&\& \ \gamma \in [0,1])$  then
      - $c = \alpha c_0 + \beta c_1 + \gamma c_2$  // Gouraud interpolation (Gouraud, 1971)
      - Draw a color  $c$  at a pixel  $(x, y)$

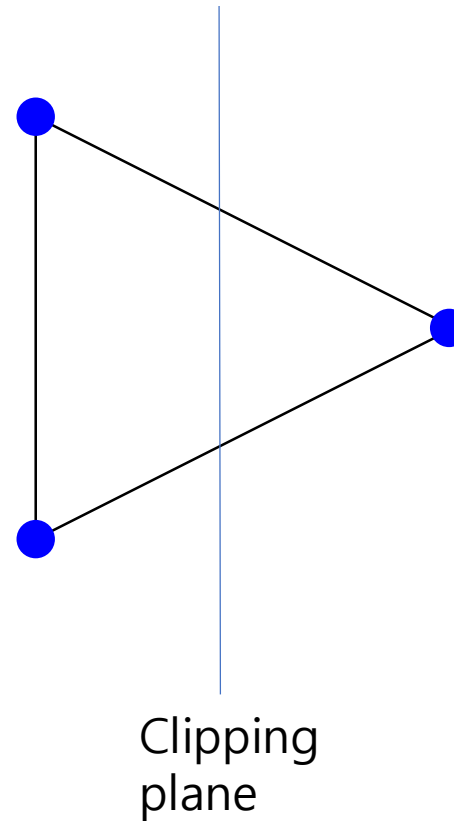
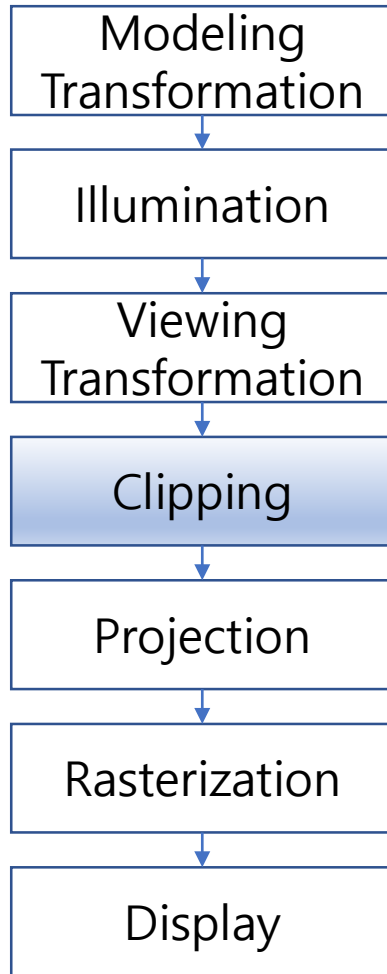


# Triangle Rasterization

- For all x **within a bounding box** do
  - For all y **within a bounding box** do
    - Compute  $\alpha, \beta, \gamma$  for  $(x, y)$
    - If  $(\alpha \in [0,1] \ \&\& \ \beta \in [0,1] \ \&\& \ \gamma \in [0,1])$  then
      - $c = \alpha c_0 + \beta c_1 + \gamma c_2$  // Gouraud interpolation (Gouraud, 1971)
      - Draw a color  $c$  at a pixel  $(x, y)$

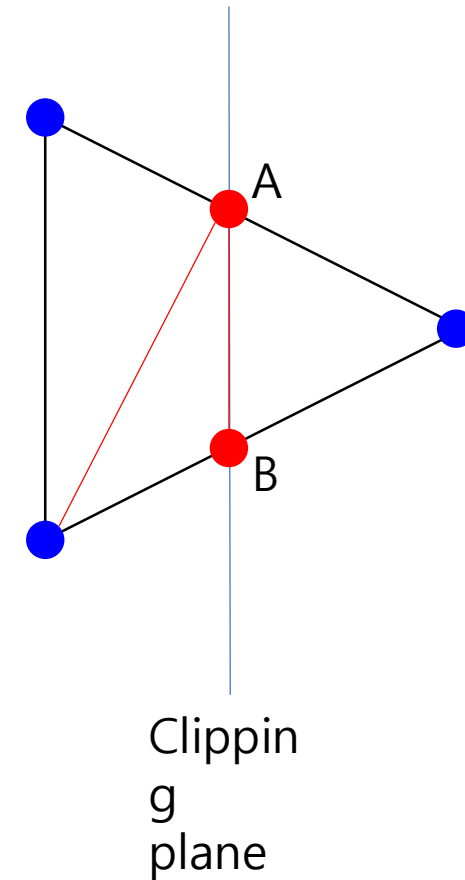


# Clipping



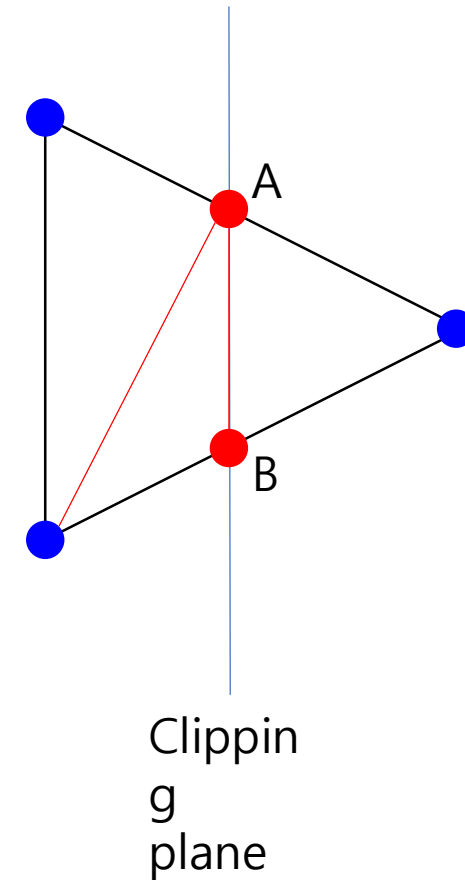
# Clipping

- A parametric line connecting  $\mathbf{a}$  and  $\mathbf{c}$ :
  - $\mathbf{p}(t) = \mathbf{a} + t(\mathbf{c} - \mathbf{a})$
- Implicit plane through point  $\mathbf{q}$  with normal  $\mathbf{n}$ :
  - $f(\mathbf{p}) = (\mathbf{p} - \mathbf{q}) \cdot \mathbf{n} = 0$
  - Can be written as:
    - $f(\mathbf{p}) = \mathbf{p} \cdot \mathbf{n} + D = 0$
  - Recall that
    - $f(\mathbf{p}) < 0$  :  $\mathbf{p}$  is inside
    - $f(\mathbf{p}) = 0$  :  $\mathbf{p}$  is on the plane
    - $f(\mathbf{p}) > 0$  :  $\mathbf{p}$  is outside



# Clipping

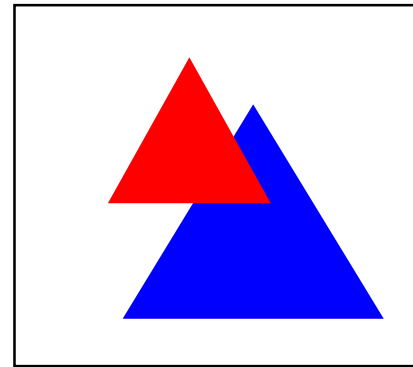
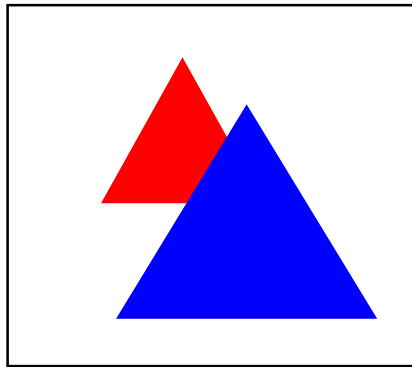
- A parametric line connecting  $\mathbf{a}$  and  $\mathbf{c}$ :
  - $\mathbf{p}(t) = \mathbf{a} + t(\mathbf{c} - \mathbf{a})$
- Implicit plane through point  $\mathbf{q}$  with normal  $\mathbf{n}$ :
  - $f(\mathbf{p}) = \mathbf{p} \cdot \mathbf{n} + D = 0$
  - If the end points of a line have different signs,
    - we need to find the intersection point between the plane and line segment
    - $(\mathbf{a} + t(\mathbf{c} - \mathbf{a})) \cdot \mathbf{n} + D = 0$
    - Solving for t:
      - $t_A = -\frac{\mathbf{n} \cdot \mathbf{a} + D}{\mathbf{n} \cdot (\mathbf{c} - \mathbf{a})}$
      - $\mathbf{A} = \mathbf{a} + t_A(\mathbf{c} - \mathbf{a})$
      - A similar computation will give B.



# Z-Buffer for Hidden Surfaces

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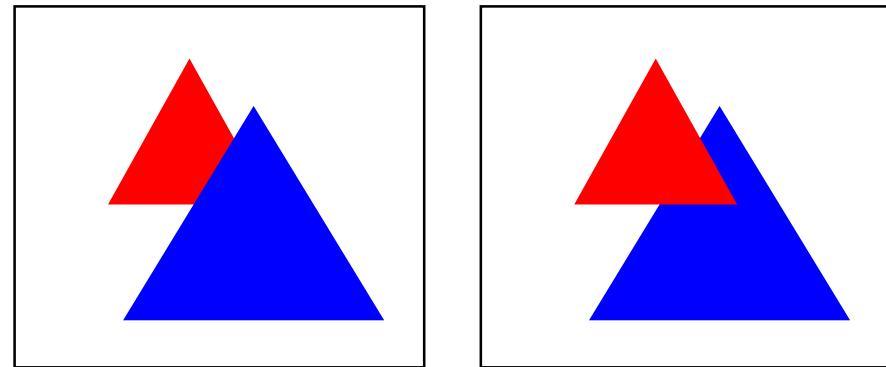
- In graphics, z-buffer (depth buffer) is used to draw closest primitives.
- Z-buffer
  - Store the depth at each pixel



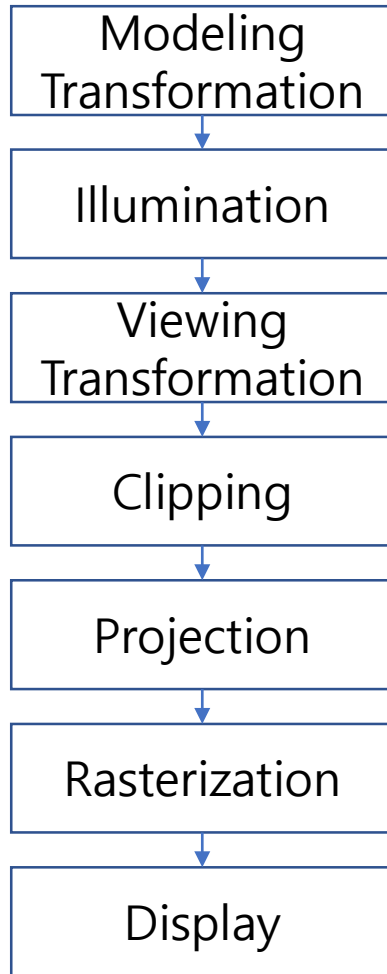
# Z-Buffer for Hidden Surfaces

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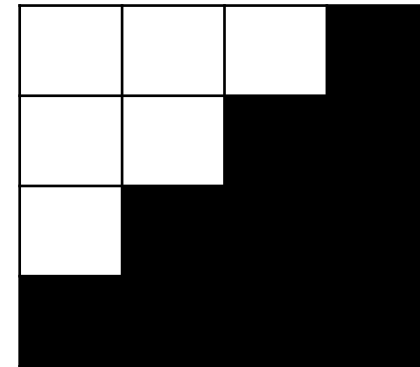
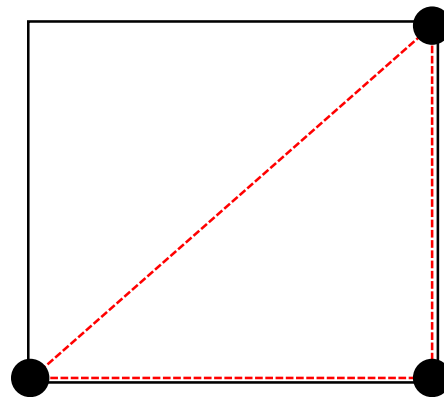
- In graphics, z-buffer (depth buffer) is used to draw closest primitives.
- Z-buffer
  - Store the depth at each pixel
- Algorithm:
  - Initialize z-buffer to the maximum depth (i.e., the depth of the far plane)
  - Interpolate the z-coordinate as a vertex attribute (similar to the color interpolation)
  - If the z value at  $(x, y) < z\text{-buffer}(x,y)$ 
    - Fill the pixel color at  $(x, y)$
    - Update the  $z\text{-buffer}(x,y)$



# Review of the Rendering Pipeline

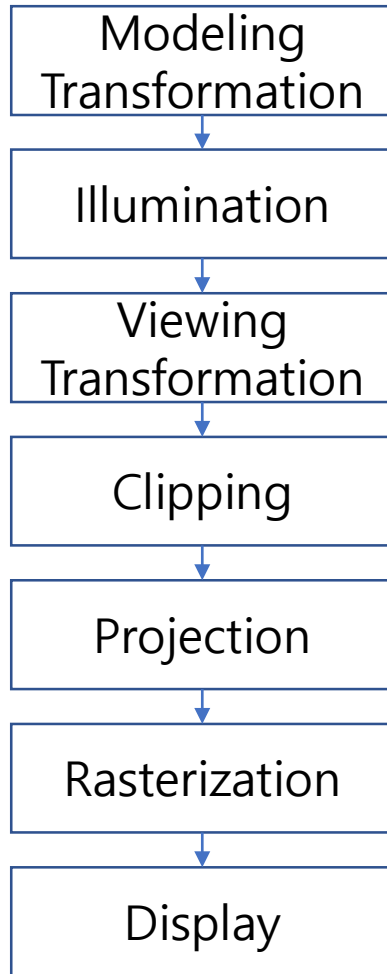


- So far, we have covered most pipeline components.
- The illumination part will be discussed later.
- Q. how do we handle aliasing?



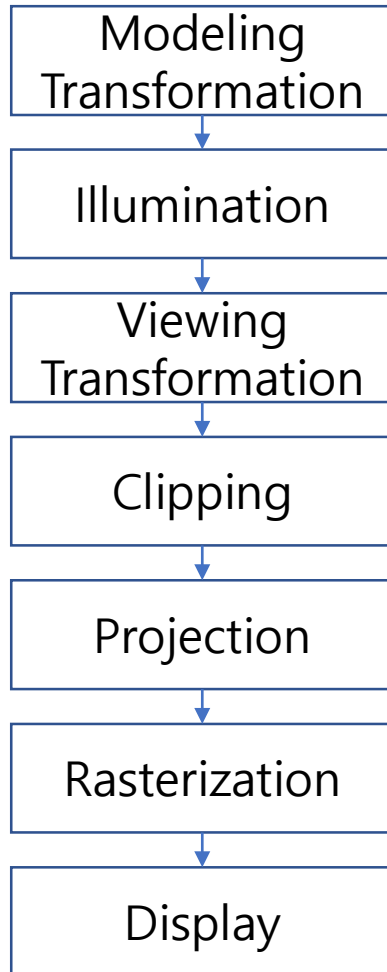
# Review of the Rendering Pipeline

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- So far, we have covered most pipeline components.
- The illumination part will be discussed later.
- Q. how do we handle aliasing?
  - Super-sampling: draw a larger image than a specified resolution, and average multiple colors with a filter (box filter)
  - Sophisticated filters can be designed.
  - 3D game may provide an option to users for this anti-aliasing.

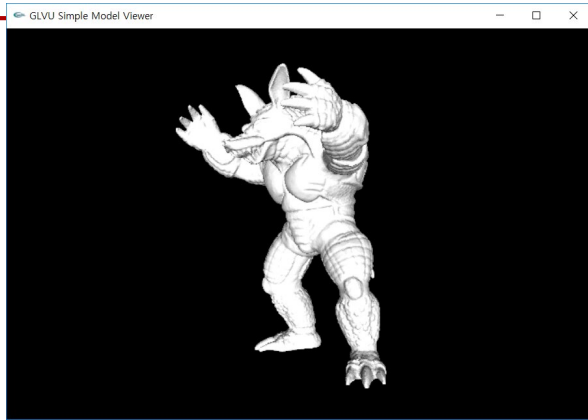
# Review of the Rendering Pipeline



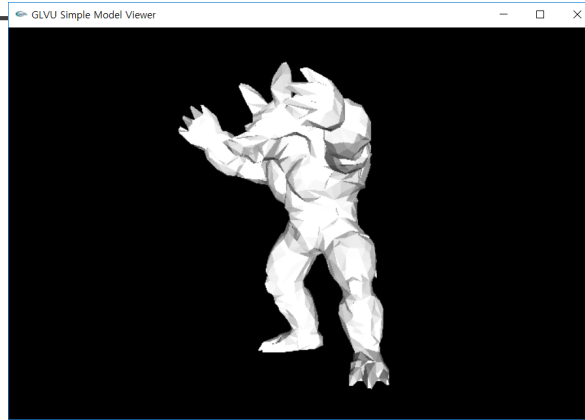
- So far, we have covered most pipeline components.
- The illumination part will be discussed later.
- Q. how do we handle aliasing?
- Q. do we have other optimization techniques?
  - Levels-of-detail (LOD)
    - Static LOD
    - Dynamic LOD
    - Stochastic Simplification of Aggregate Detail, [Cook et al. SIG 07]



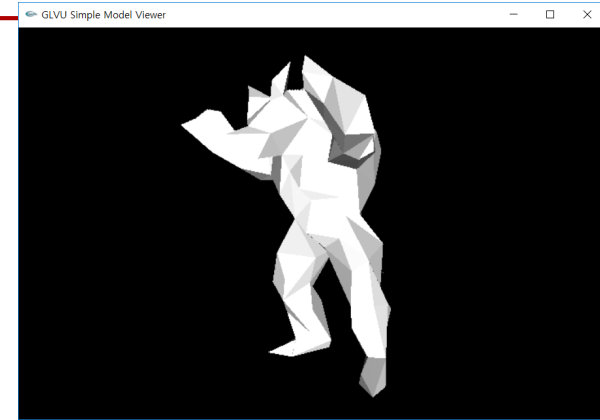
# Review of the Rendering Pipeline



345944 tri.



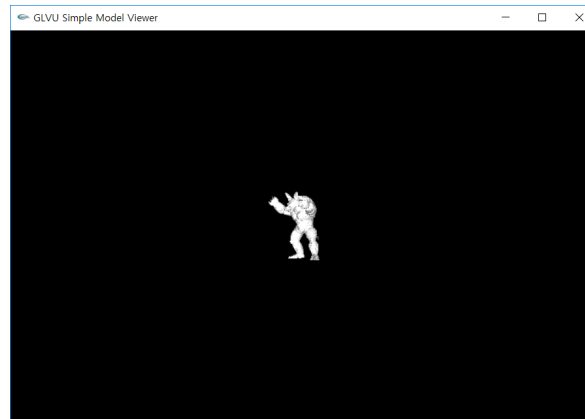
3000 tri.



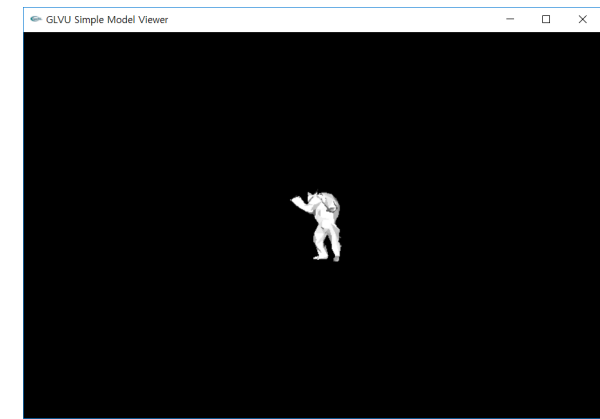
300 tri.



345944 tri.



3000 tri.



300 tri.

# Further Readings

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- Chapter 8
- Chapter 12.4