

Lecture slides (CT4201/EC4215 – Computer Graphics)

OpenGL: Setup 3D World

Lecturer: Bochang Moon



Computer Graphics
Laboratory

Prerequisite for 3D World

- Understanding on basic mathematical background, transformations, and spaces
 - Pixels, raster image, ...
 - Vector, matrix, ...
 - Model, viewing, and projection transformations
 - Object, world, eye, canonical view, and screen space



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3D Model

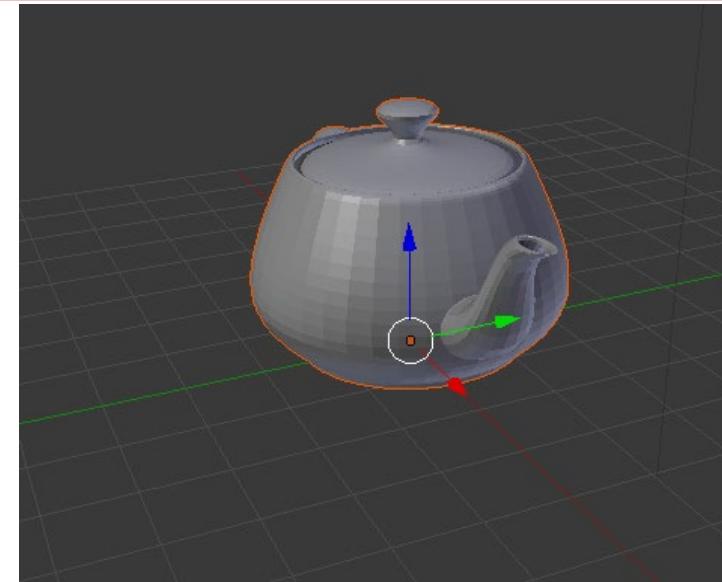
- Definition of a model (or object) in 3D
 - Vertex
 - Normal (optional)
 - Q. Why do we need to use the vertex normal?
 - Texture coordinates (optional)
 - Face (usually triangles)
 - etc.
- File format for 3D models
 - You can make your own format only for your program.
 - Common formats
 - 3DS, MAX, ply (Stanford graphics lab), obj (Wavefront), etc.
 - Simple formats
 - ply and obj are quite simple formats
 - In this course, we will use “obj” format as this can be used in most rendering engines.



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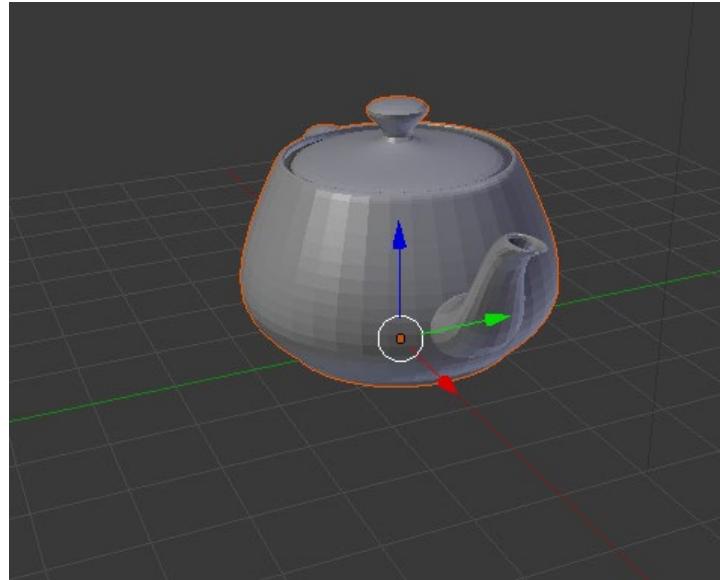
Example: .obj File Format

- Artists (or you) can design 3D models in some modeling tools (e.g., blender).
 - Out of scope...
- Most modeling tools allow us to store the models in .obj format.
 - For your homework, .obj files will be given.



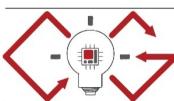
Example: .obj File Format

```
v -3.000000 1.800000 0.000000 f 2909 2921 2939  
v -2.991600 1.800000 -0.081000 f 2939 2931 2909  
v -2.991600 1.800000 0.081000 f 2869 2877 2921  
v -2.989450 1.666162 0.000000 f 2921 2909 2869  
v -2.985000 1.921950 0.000000 f 2819 2827 2877  
v -2.985000 1.921950 0.000000 f 2877 2869 2819  
v -2.981175 1.667844 -0.081000 f 2737 2747 2827  
v -2.981175 1.667844 0.081000 f 2827 2819 2737  
v -2.976687 1.920243 -0.081000 f 2669 2673 2747  
v -2.976687 1.920243 0.081000 f 2747 2737 2669  
v -2.968800 1.800000 -0.144000 f 2567 2575 2673  
v -2.968800 1.800000 0.144000 f 2673 2669 2567  
v -2.958713 1.672406 -0.144000 f 2476 2480 2575  
v -2.958713 1.672406 0.144000 f 2575 2567 2476  
v -2.957600 1.534800 0.000000 f 2358 2362 2480  
v -2.957600 1.534800 0.000000 f 2480 2476 2358  
v -2.954122 1.915609 -0.144000 f 2158 2162 2362  
v -2.954122 1.915609 0.144000 f 2362 2358 2158  
v -2.949693 1.537790 -0.081000 f 1715 1812 2162  
v -2.949693 1.537790 0.081000 f 2162 2158 1715  
v -2.940000 2.019600 0.000000 f 2901 2909 2931  
v -2.935200 1.800000 -0.189000 f 2931 2917 2901  
v -2.935200 1.800000 0.189000 f 2863 2869 2909  
v -2.931958 2.016526 0.081000 f 2909 2901 2863  
v -2.931958 2.016526 -0.081000 f 2813 2819 2869  
v -2.928230 1.545907 -0.144000 f 2869 2863 2813  
v -2.928230 1.545907 0.144000 f 2729 2737 2819  
v -2.925611 1.679131 -0.189000 f 2819 2813 2729  
v -2.925611 1.679131 0.189000 f 2663 2669 2737  
v -2.920870 1.908779 -0.189000 f 2737 2729 2663  
v -2.920870 1.908779 0.189000 f 2561 2567 2669  
v -2.910131 2.008181 -0.144000 f 2669 2663 2561  
v -2.910131 2.008181 0.144000 f 2468 2476 2567  
v -2.904150 1.406137 0.000000 f 2567 2561 2468  
v -2.904150 1.406137 0.000000 f 2350 2358 2476  
v -2.896846 1.410135 0.081000 f 2476 2468 2350  
v -2.896846 1.410135 -0.081000 f 2152 2158 2358  
v -2.896602 1.557869 -0.189000 f 2358 2350 2152  
v -2.896602 1.557869 0.189000 f 1717 1715 2158  
v -2.894400 1.800000 -0.216000 f 2158 2152 1717  
v -2.894400 1.800000 0.216000 f 2903 2901 2917
```



teapot.obj (toy example)

- 3644 vertices
- 6320 faces



Example: .obj File Format

- #: comment line
- v x y z w
 - Vertex coordinates in model space
 - w: optional (default = 1)
- vt u v
 - Texture coordinates ($0 \leq u, v \leq 1$)
- vn x y z
 - Normal direction
- f v1 v2 v3
 - v1: index in the vertex list (integer)
- Q. why do they use the vertex index instead of coordinates?



Example: .obj File Format

- f v1 v2 v3
 - v1: index in the vertex list (integer)
- f v1/vt1 v2/vt2 v3/vt3
 - vt: texture coordinate (index)
- f v1/vt1/vn1 v2/vt2/vn2 v3/vt3/vn3
 - vn: normal (index)
- f v1//vn1 v2//vn2 v3//vn3
 - Need empty slash to avoid ambiguity



Loading .obj Model

- Read .obj files from your disk
 - Build a vertex list from each model
 - (optional) Create normal and texture coordinate lists
 - Build a face list
 - In our example, we will use triangles.
- A very simple .obj loader will be given for your assignments.
 - ModelLoader.h & ModelLoader.cpp



Draw Triangles

- For each triangle in a model
 - glBegin(GL_TRIANGLES)
 - For each vertex in a triangle
 - glVertex3d(x, y, z)
 - (optionally)
 - glNormal3d(nx, ny, nz) // related to shading
 - glTexCoord2d(u, v) // related to texture mapping
 - glEnd()



OpenGL Display List

- Display list: a set of OpenGL commands that have been stored for later execution
- Once the list is compiled (one time), it can be re-used multiple times.
 - Very efficient for static models



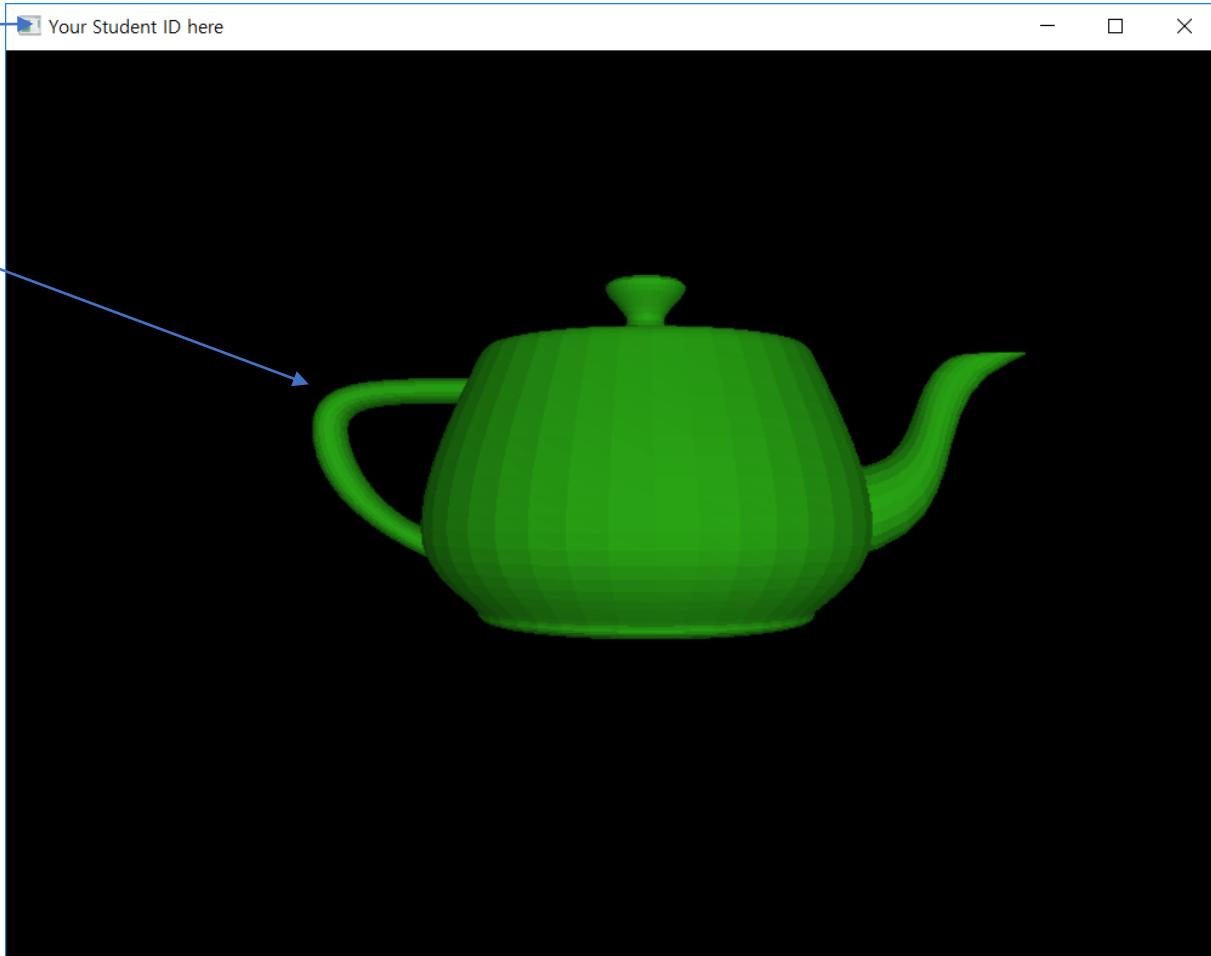
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Example of OpenGL Display List

- `g_teapotID = glGenLists(1) // create a list and store the ID to the variable`
 - `glNewList(g_teapotID, GL_COMPILE) // Define the set of commands`
 - `glBegin(GL_TRIANGLES)`
 - For each vertex in a triangle
 - `glVertex3d(x, y, z)`
 - (optionally)
 - `glNormal3d(nx, ny, nz) // related to shading`
 - `glTexCoord2d(u, v) // related to texture mapping`
 - `glEnd()`
 - `glEndList()`
-
- Draw some models with IDs
 - `glCallList(g_teapotID)`

Result Image

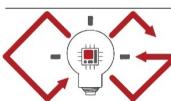
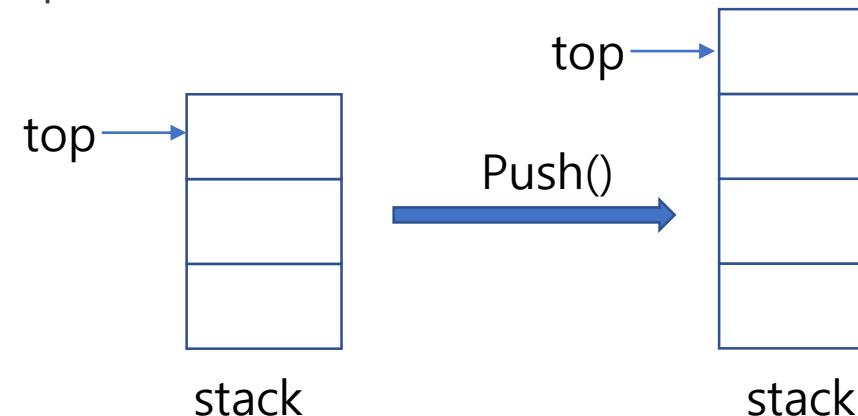
- Title bar



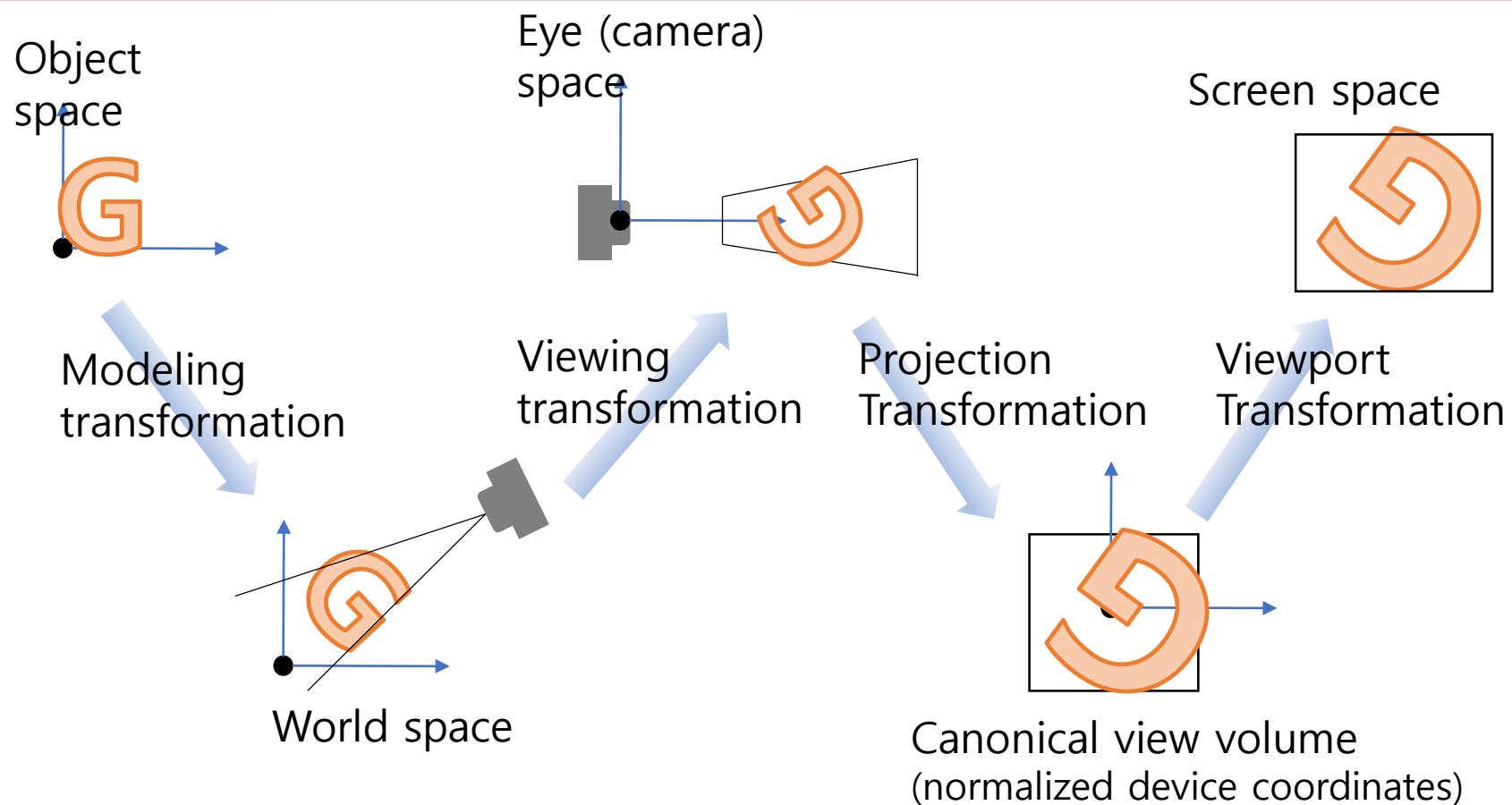
- Teapot model
 - A set of triangles

OpenGL Matrix Mode

- `glMatrixMode(mode)`
 - mode: specify which matrix stack is the target that we want to modify
 - `GL_PROJECTION`
 - `GL_MODELVIEW`
 - `GL_TEXTURE` (not used now)
- Stack?
 - An abstract data structure that can contain multiple elements
 - LIFO: Last In First Out
 - Interfaces
 - Push: insert a new element into the stack
 - Pop: delete an element from the stack
 - The top element can be modified.



Sequence of Spaces and Transformations



OpenGL Matrix Mode

- `glMatrixMode(mode)`
 - mode: specify which matrix stack is the target that we want to modify
 - `GL_PROJECTION`
 - `GL_MODEL_VIEW`
 - `GL_TEXTURE` (not used now)
 - `GL_PROJECTION`
 - Related to the projection transformation
 - `GL_MODEL_VIEW`
 - Related to the modeling and viewing transformation
 - Should call this function first before applying a transformation



OpenGL Matrix Mode

- void reshape(int w, int h)
 - glViewport(0, 0, w, h); // viewport transformation is specified.
 - glMatrixMode(GL_PROJECTION); // specify our target stack
 - glLoadIdentity(); // set the current matrix as the identity
 - gluPerspective(fov, aspect, near, far); // change the current matrix with the perspective transformation matrix



stack (projection)



stack (model view)



OpenGL Matrix Mode

- void reshape(int w, int h)
 - glViewport(0, 0, w, h); // viewport transformation is specified.
 - glMatrixMode(GL_PROJECTION); // specify our target stack
 - glLoadIdentity(); // set the current matrix as the identity
- Alternatively,
 - We can explicitly construct the projection matrix
 - double matrix[16] = {...}
 - glMultMatrixd(matrix); // multiply the current matrix with the specified matrix



stack (projection)



stack (model view)



OpenGL Matrix Mode

- void reshape(int w, int h)
 - glViewport(0, 0, w, h); // viewport transformation is specified.
 - glMatrixMode(GL_PROJECTION); // specify our target stack
 - glLoadIdentity(); // set the current matrix as the identity
 - gluPerspective(fov, aspect, near, far); // change the current matrix with the perspective transformation matrix
- glMatrixMode(GL_MODELVIEW);
- glLoadIdentity();



stack (projection)

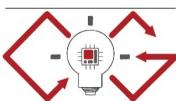
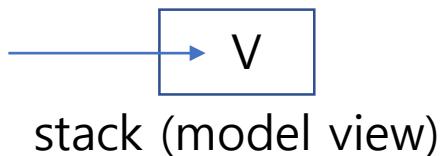


stack (model view)



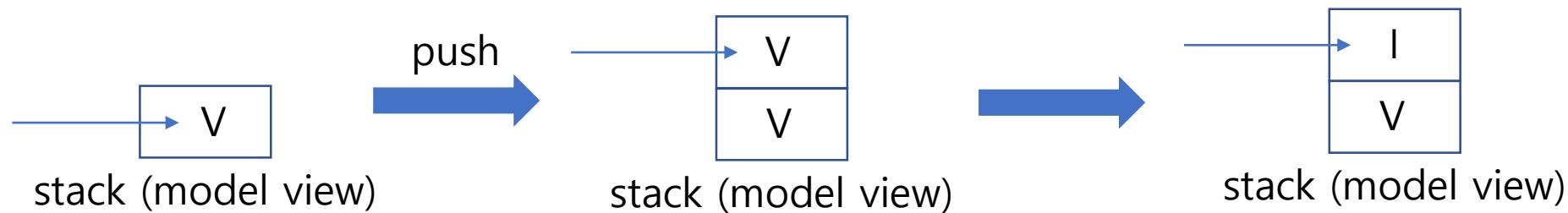
OpenGL Matrix

- void display()
 - glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT)
 - setCamera() // specify the viewing transformation (change the current matrix)
 - e.g., gluLookAt() or explicitly build the matrix



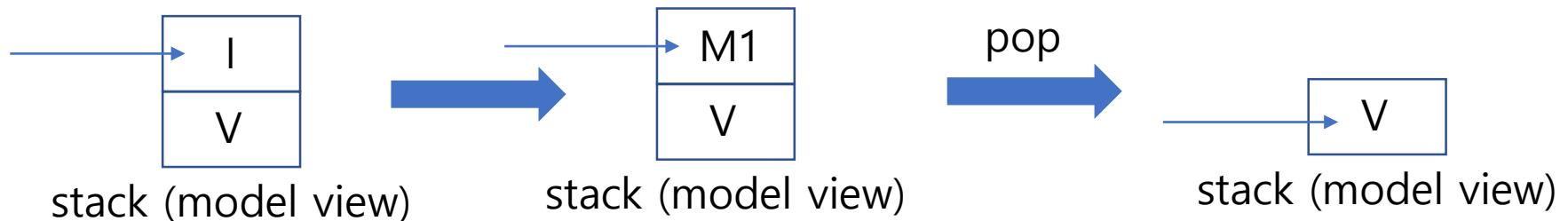
OpenGL Matrix

- For each model
 - `glPushMatrix();` // push down the current matrix, and insert a new element it to the stack
(the new matrix will be equal to the current matrix - duplicated)
 - `glLoadIdentity();` // initialize the current matrix



OpenGL Matrix

- For each model (continued...)
 - // specify modeling transformation matrix
 - e.g., $M = T$, $M = RT$, and etc.
 - e.g., call predefined functions (`glTranslated(...)`, `glRotated(...)`) or explicitly build the matrix and multiply it
 - e.g., `glTranslated(...)` // build the specified translation matrix and multiply it to the current matrix
 - // draw primitives
 - e.g., `glCallList(ID)` // use the display list
 - // pop the modeling transformation – why?
 - `glPopMatrix()`



OpenGL Matrix

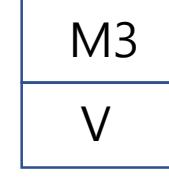
- Scenarios
 - Each model has different modeling transformations
 - The matrix stack (with different modeling matrix) should be built before drawing the primitives of each model



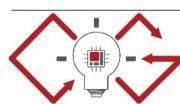
stack (model view)



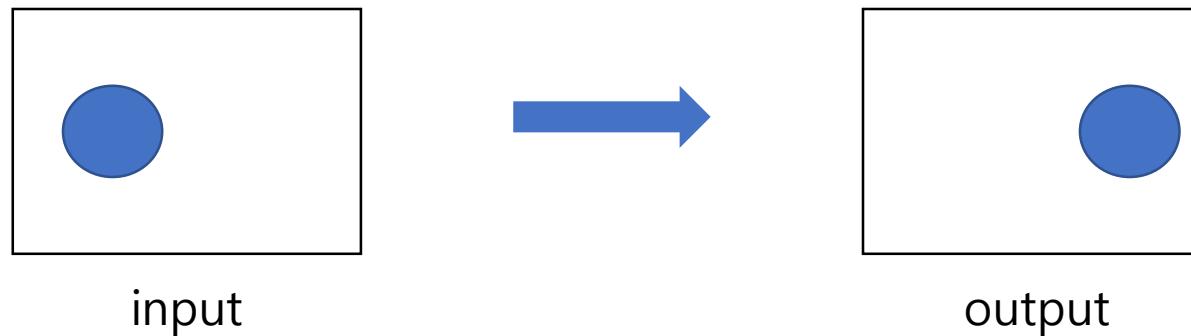
stack (model view)



stack (model view)

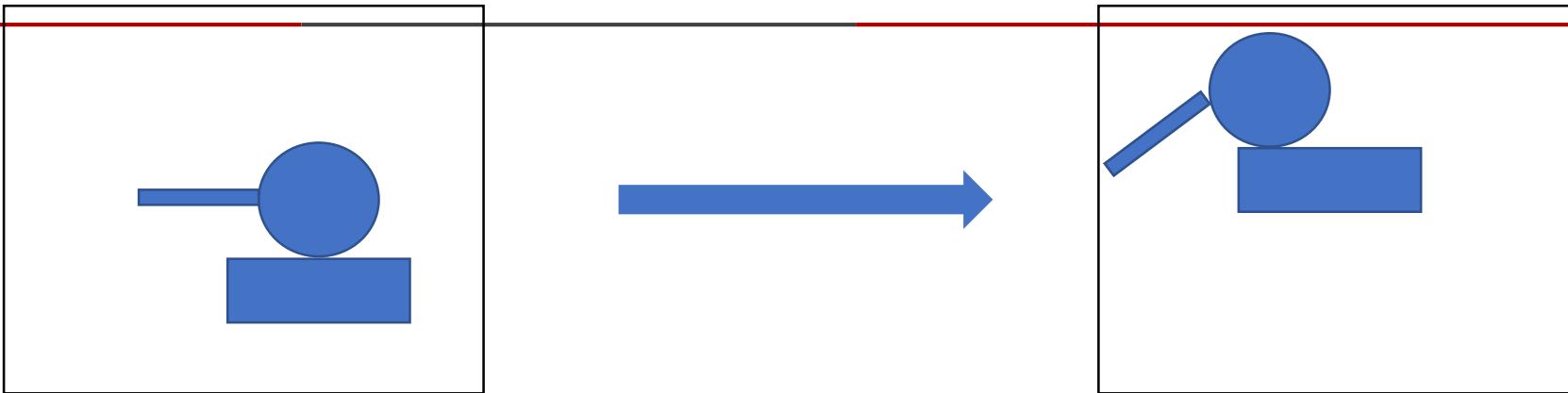


Object vs Camera Transformation



- Use modeling transformation
 - Translate the object along x direction (this can be separately applied to each object)
- Use viewing transformation
 - Translate our camera along -x direction (this moves the coordinate system – all objects will be transformed)

Hierarchical Transformation



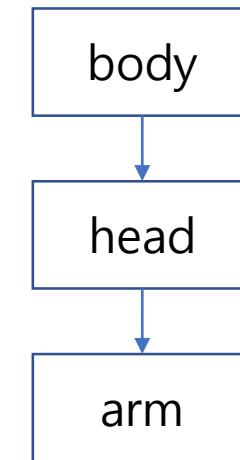
Two ways of achieving this transformation:

1. Apply different transformation to each part

- Translate the body
- Translate the head
- Rotate and translate the arm

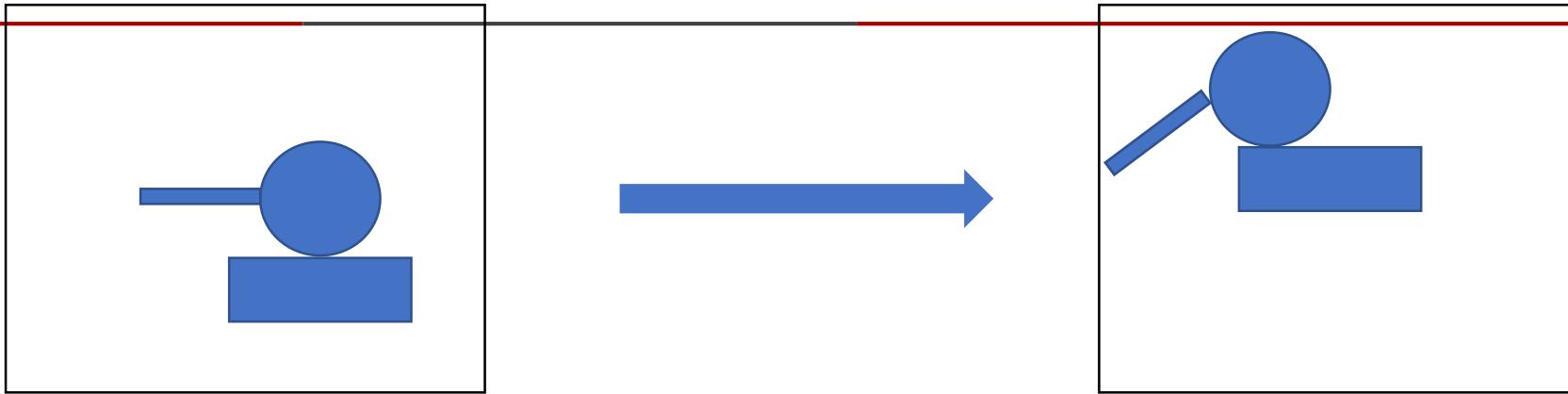
2. Utilize relative transformation

- Some parts can depend on others
- Specify each object's transformation relative to its parent

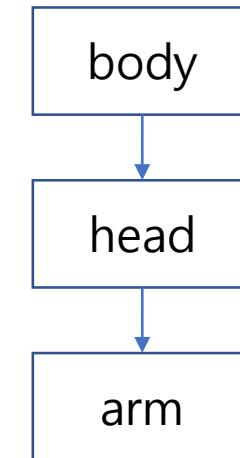


Scene graph

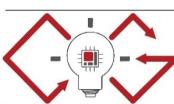
Hierarchical Transformation



2. Utilize relative transformation
 - Translate the body and its descendants
 - Translate the head and its descendant
 - Rotate the arm



Scene graph



Hierarchical Transformation

2. Utilize relative transformation

```
// apply a transformation to the body and its descendants
```

```
glTranslated(...)
```

```
// draw body
```

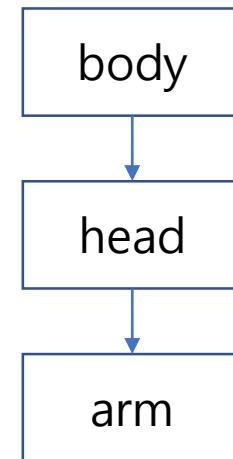
```
glTranslated(...)
```

```
// draw head
```

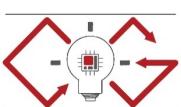
```
// apply a transformation to the arm
```

```
glRotated(..)
```

```
// draw arm
```



Scene graph



Hierarchical Transformation

2. Utilize relative transformation

```
// apply a transformation to the body and its descendants
```

```
glTranslated(...)
```

```
// draw body
```

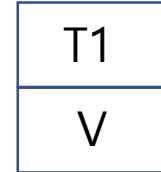
```
glTranslated(...)
```

```
// draw head
```

```
// apply a transformation to the arm
```

```
glRotated(..)
```

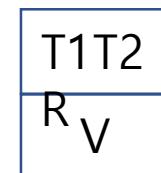
```
// draw arm
```



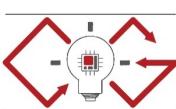
stack (model view)



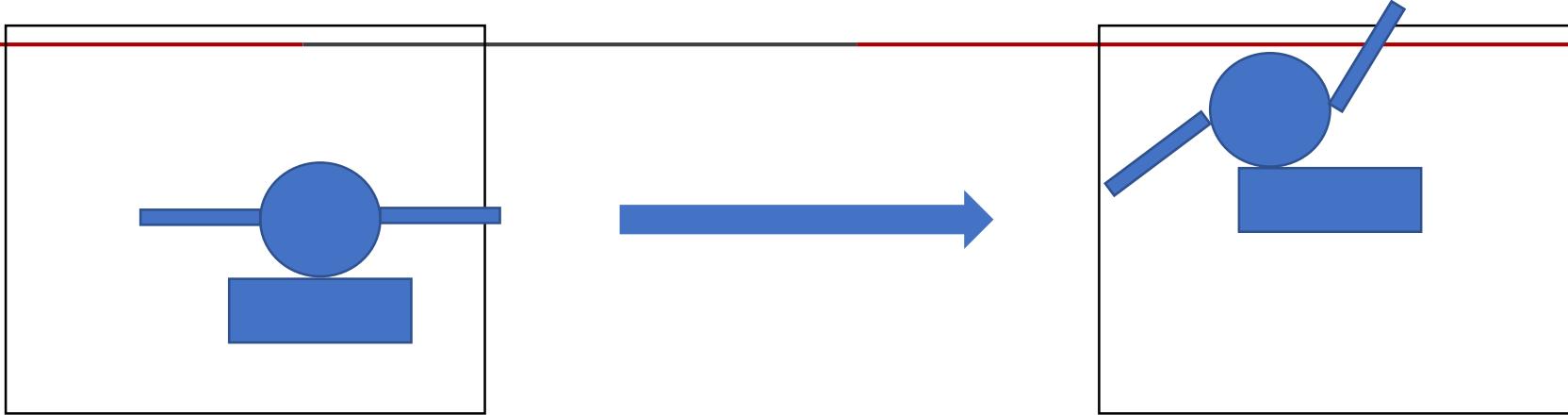
stack (model view)



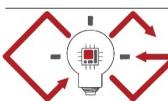
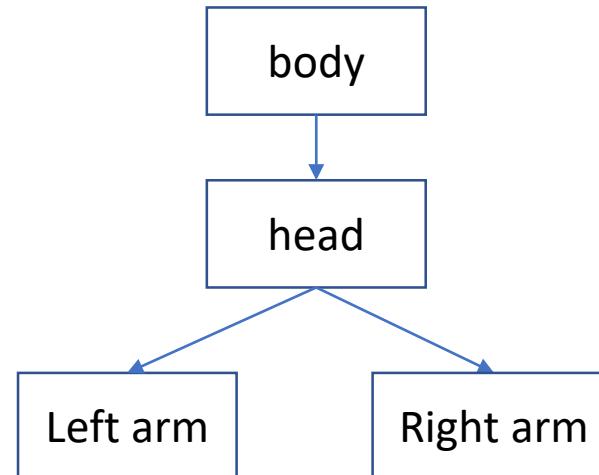
stack (model view)



Hierarchical Transformation



2. Utilize relative transformation
 - Translate the body and its descendants
 - Translate the head and its descendants
 - Rotate the left arm
 - Rotate the right arm?



Hierarchical Transformation

2. Utilize relative transformation

```
// apply a transformation to the body and its descendants
```

```
glTranslated(...)
```

```
// draw body
```

```
glTranslated(...)
```

```
// draw head
```

```
// apply a transformation to the left arm
```

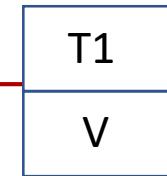
```
glRotated(..)
```

```
// draw left arm
```

```
// apply a transformation to the right arm
```

```
glRotated(..)
```

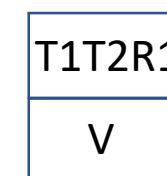
```
// draw right arm?
```



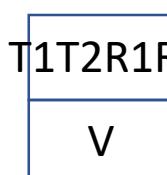
stack (model view)



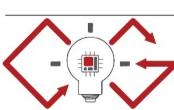
stack (model view)



stack (model view)



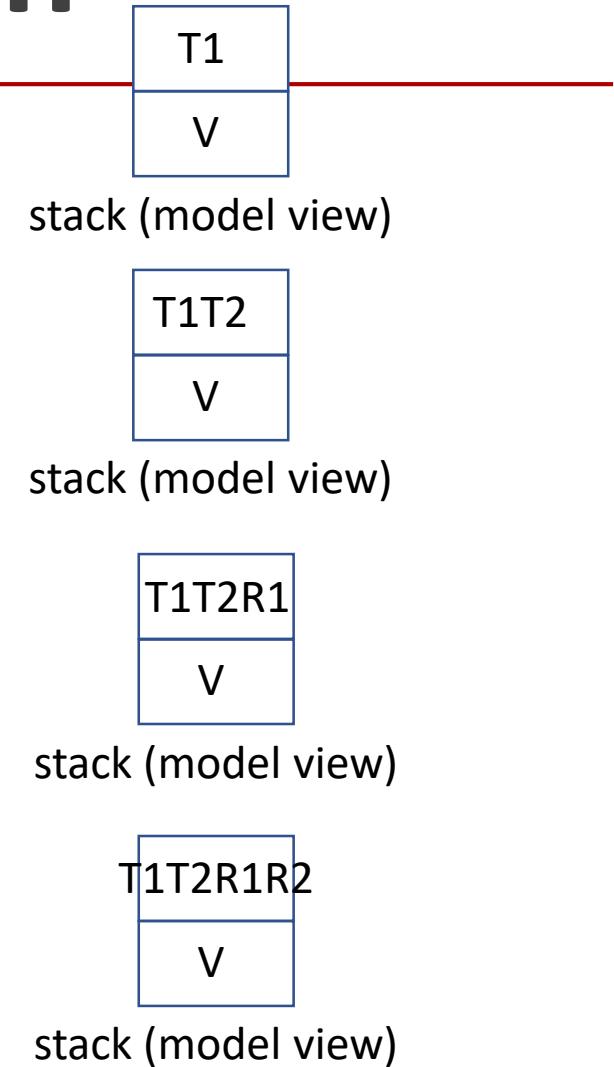
stack (model view)



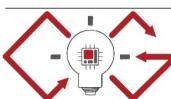
Hierarchical Transformation

2. Utilize relative transformation

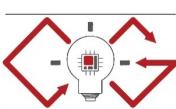
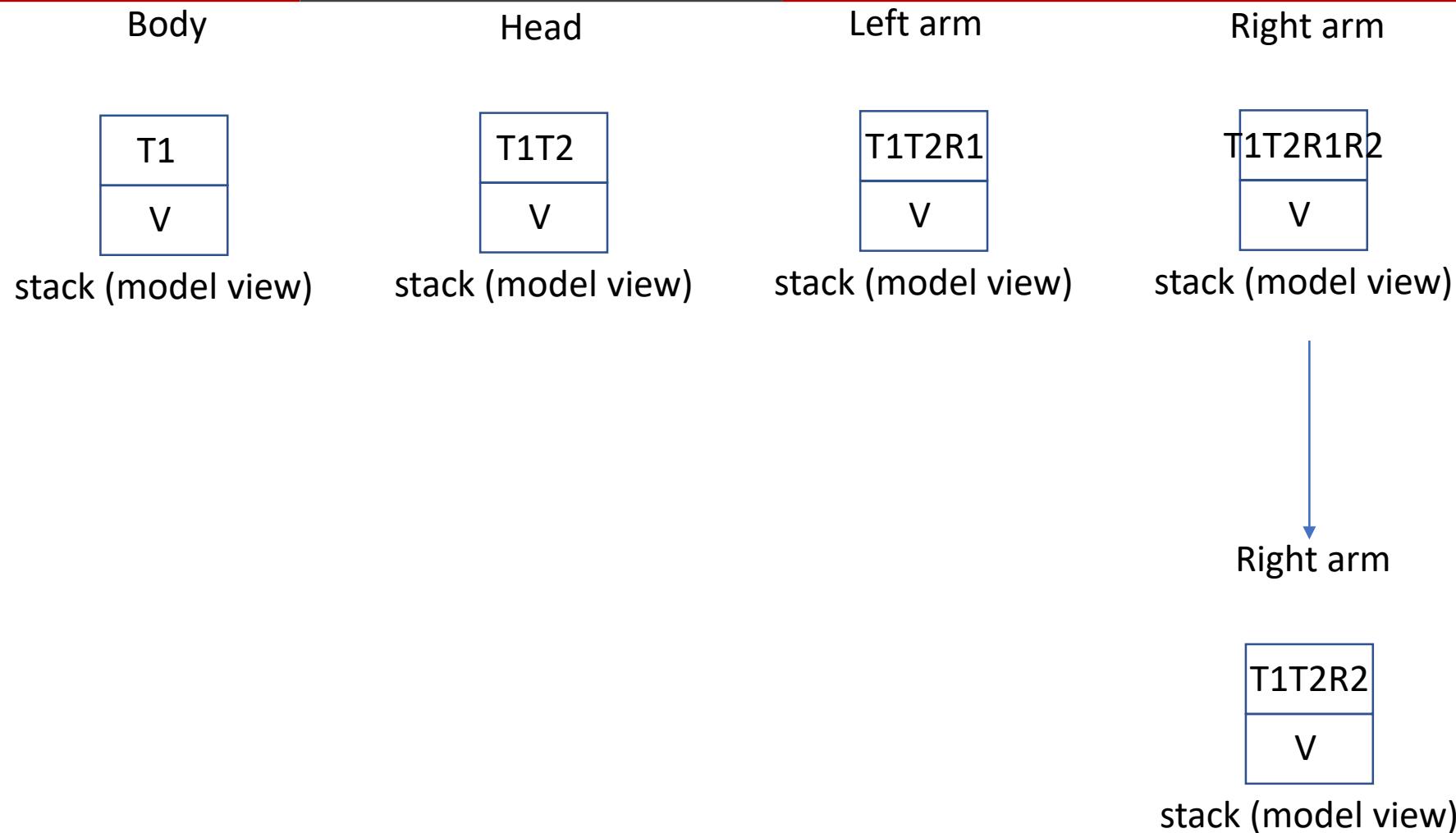
```
// apply a transformation to the body and its descendants  
glTranslated(...)  
// draw body  
glTranslated(...)  
// draw head  
  
// apply a transformation to the left arm  
glRotated(..)  
  
// draw left arm  
  
// apply a transformation to the right arm  
glRotated(..)  
  
// draw right arm?
```



ERROR: the left arm is not a parent of the right arm



Hierarchical Transformation



Hierarchical Transformation

2. Utilize relative transformation

```
// apply a transformation to the body and its descendants
```

```
glTranslated(...)
```

```
// draw body
```

```
glTranslated(...)
```

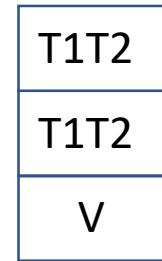
```
// draw head
```

```
// Store the current matrix!
```

```
glPushMatrix()
```



stack (model view)



stack (model view)

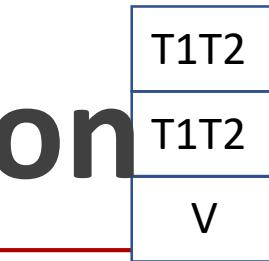
Hierarchical Transformation

```
// Store the current matrix!
glPushMatrix()
```

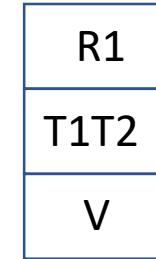
```
// apply a transformation to the left arm
glLoadIdentity()
glRotated(..)
```

```
// draw left arm
```

```
// Pop the top of the stack
glPopMatrix()
```



stack (model view)



stack (model view)



stack (model view)



Hierarchical Transformation

```
// Store the current matrix!
glPushMatrix()
```

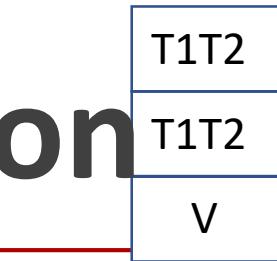
```
// apply a transformation to the left arm
glLoadIdentity()
glRotated(..)
```

```
// draw left arm
```

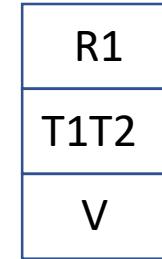
```
// Pop the top of the stack
glPopMatrix()
```

```
// apply a transformation to the right arm
glRotated(..)
```

```
// draw right arm
```



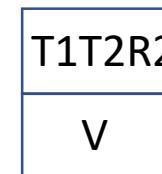
stack (model view)



stack (model view)



stack (model view)



stack (model view)

