

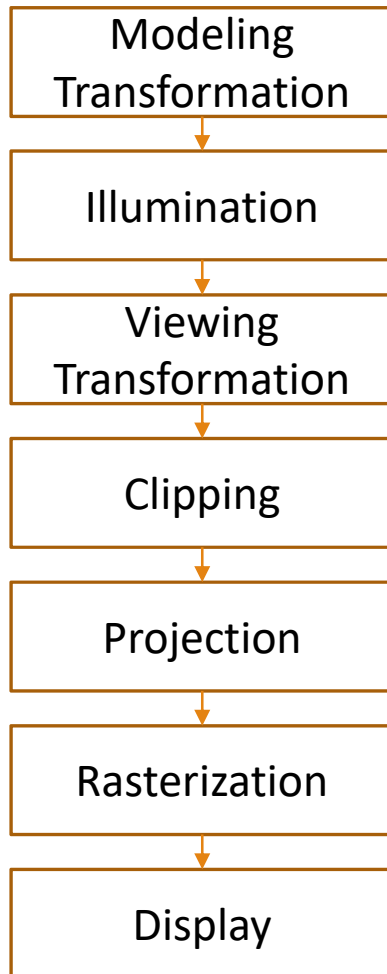
CT5510: Computer Graphics

Projections

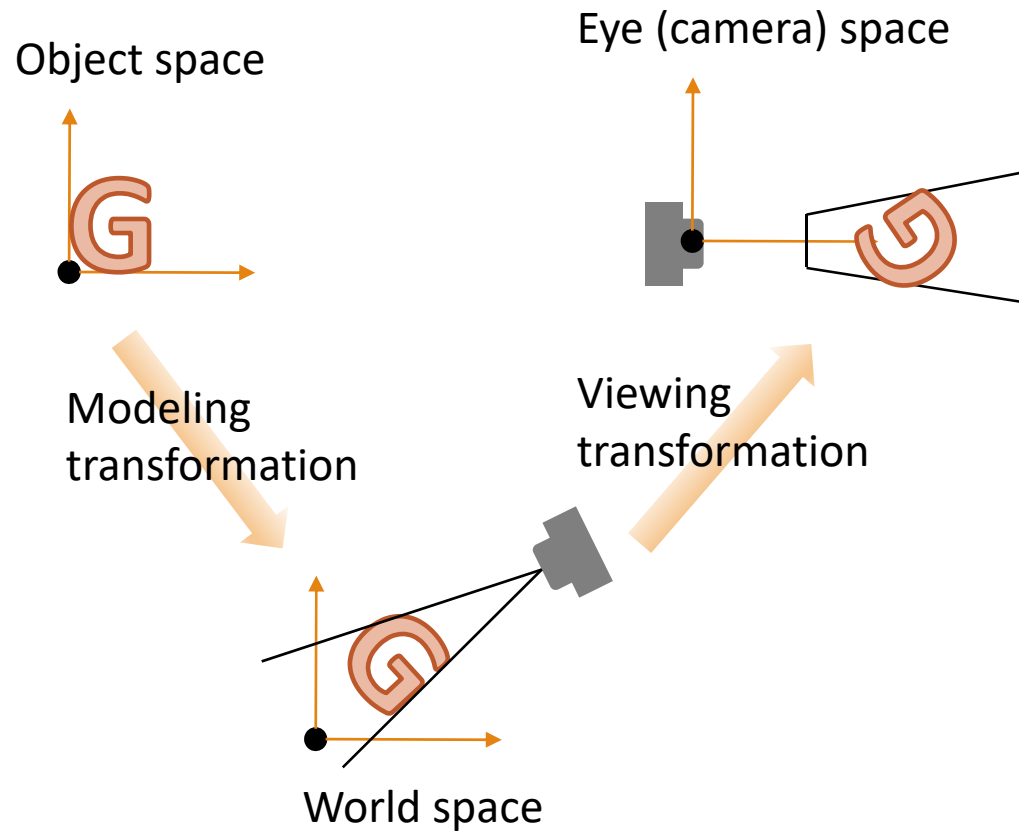
BOCHANG MOON



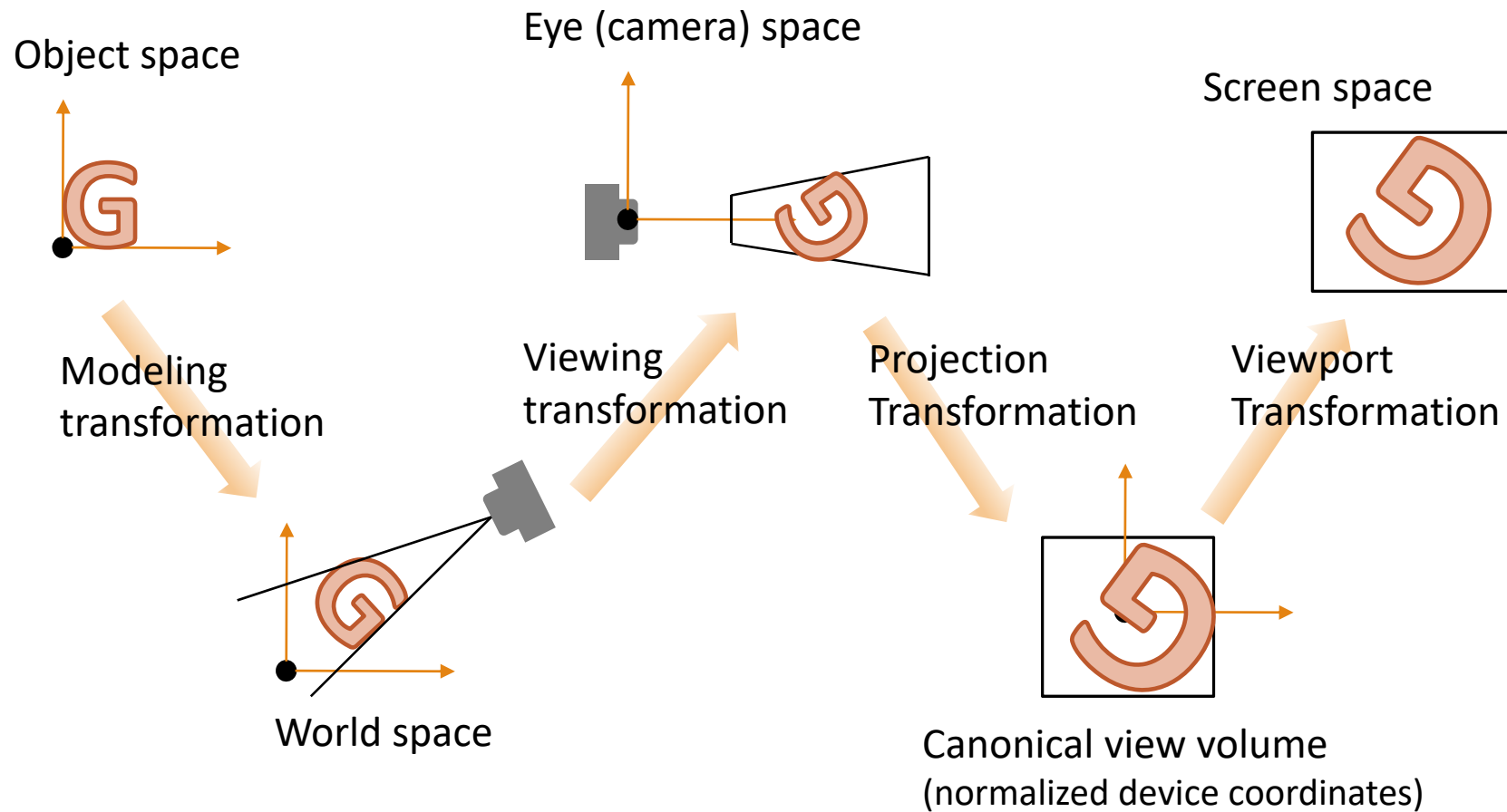
Graphics Pipeline



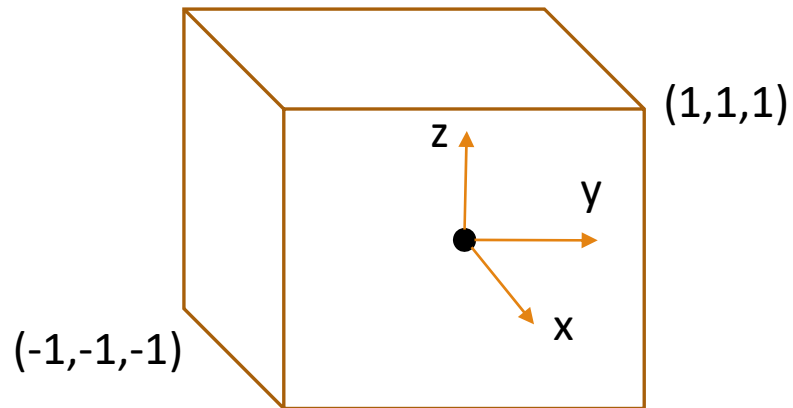
Sequence of Spaces and Transformations



Sequence of Spaces and Transformations

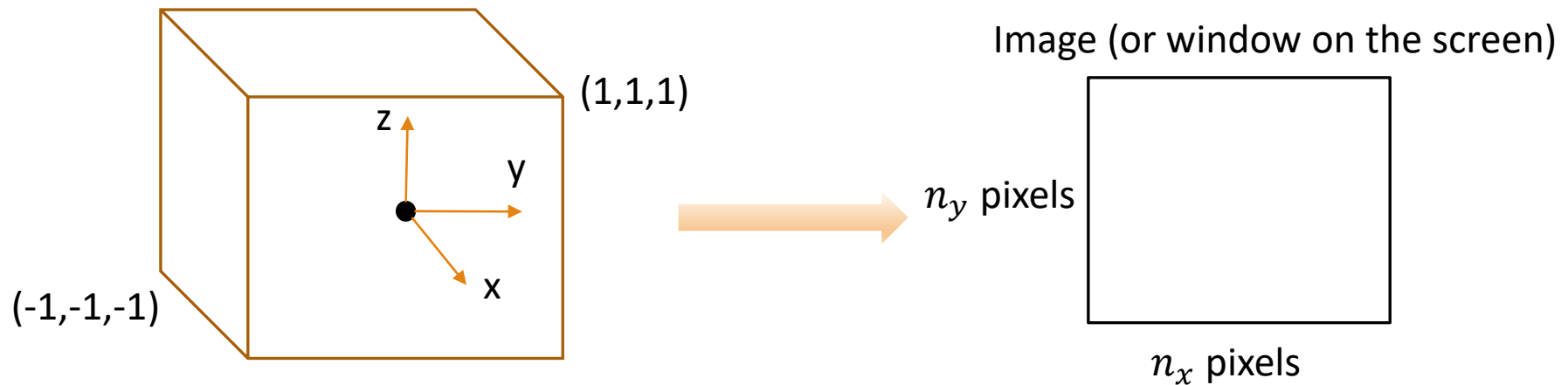


Canonical View Volume



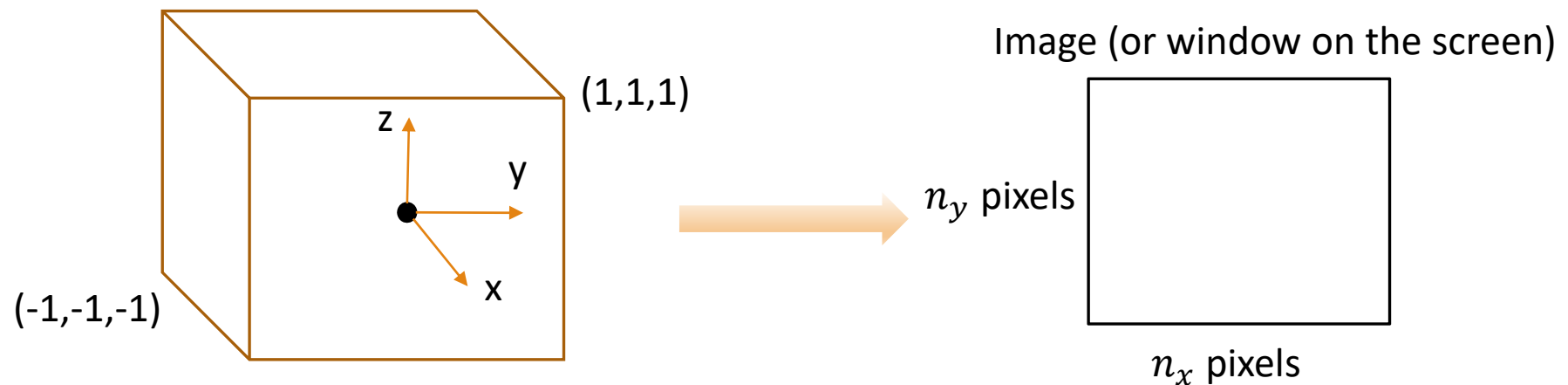
Viewport Transformation

- Primitives (or line segments) within the canonical view volume will be mapped to the image



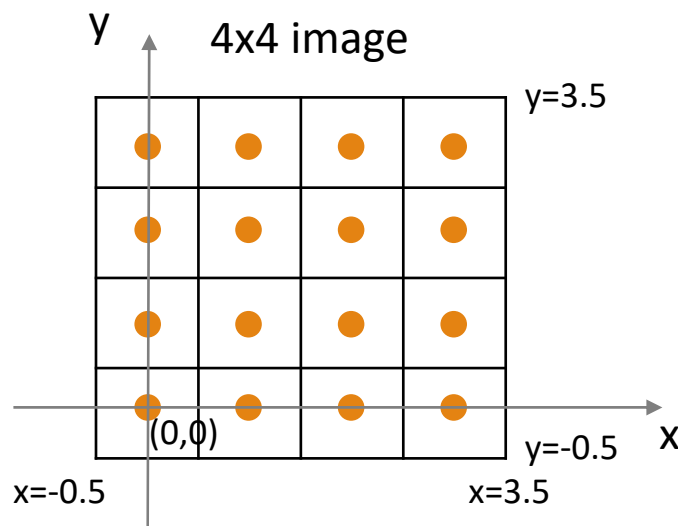
Viewport Transformation

- Ignore the z-coordinates of points for now
 - In practice, we need the z-coordinates and this will be covered later.
- Map the square $[-1,1]^2$ to the rectangle $[-0.5, n_x - 0.5] \times [-0.5, n_y - 0.5]$



Raster Image (again)

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- Where do we need to locate pixels in 2D space?



Raster Image (again)

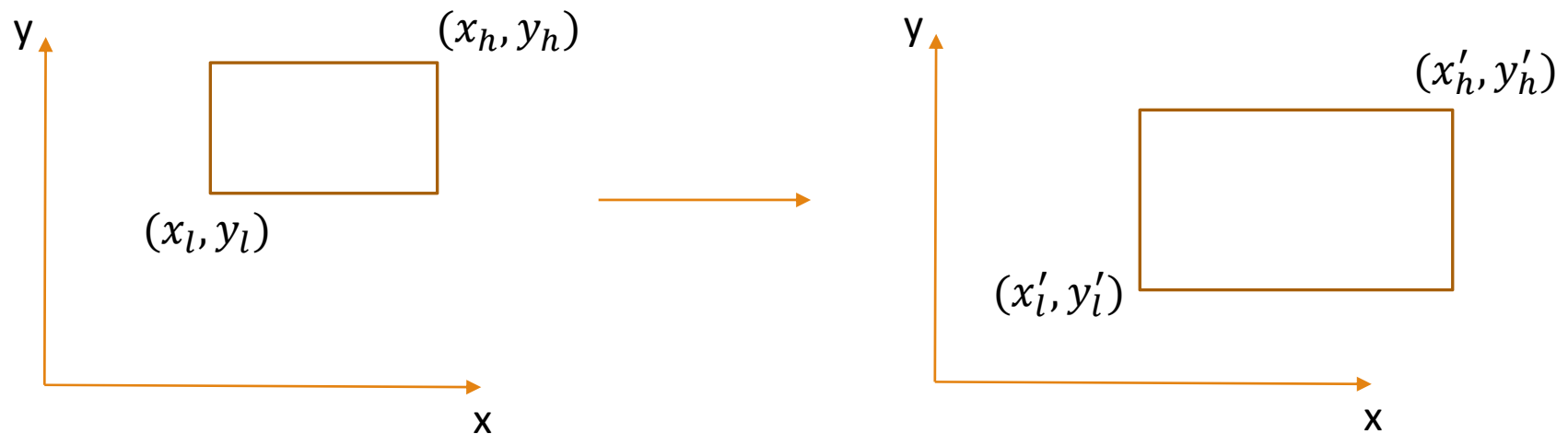
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- Map the square $[-1,1]^2$ to the rectangle $[-0.5, n_x - 0.5] \times [-0.5, n_y - 0.5]$
- Where do we need to locate pixels in 2D space?
- The rectangular domain of a $n_x \times n_y$ image
 - $R = [-0.5, n_x - 0.5] \times [-0.5, n_y - 0.5]$

Viewport Transformation

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- Map the square $[-1,1]^2$ to the rectangle $[-0.5, n_x - 0.5] \times [-0.5, n_y - 0.5]$
- Q. How do we transform a rectangle to another rectangle?

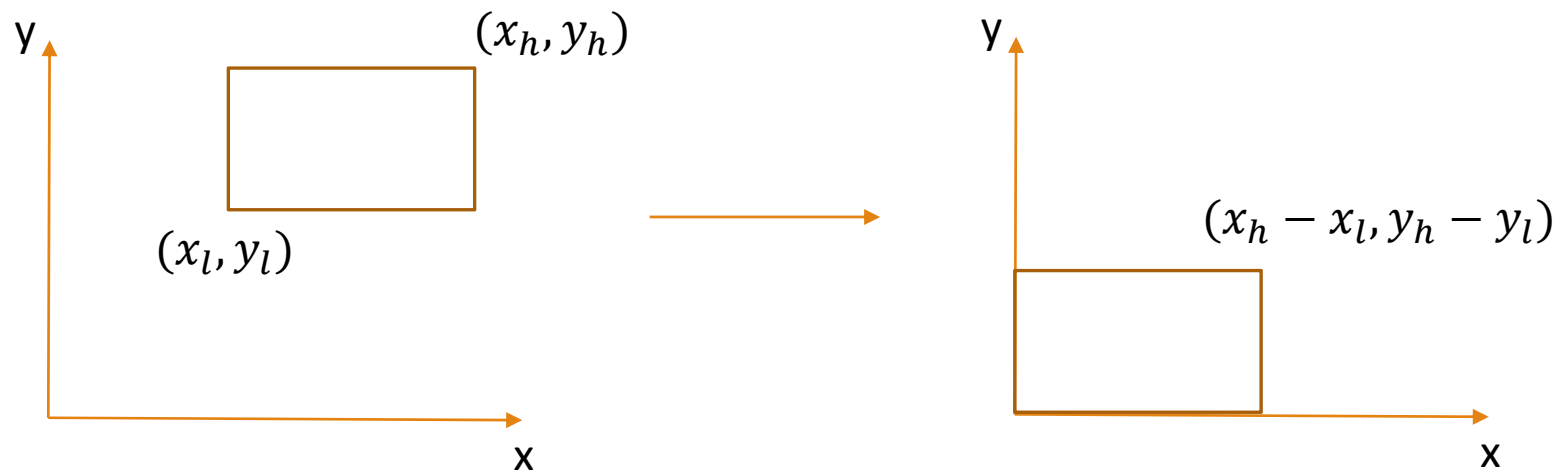
Example: Windowing Transform

- Problem specification: move a 2D rectangle into a new position



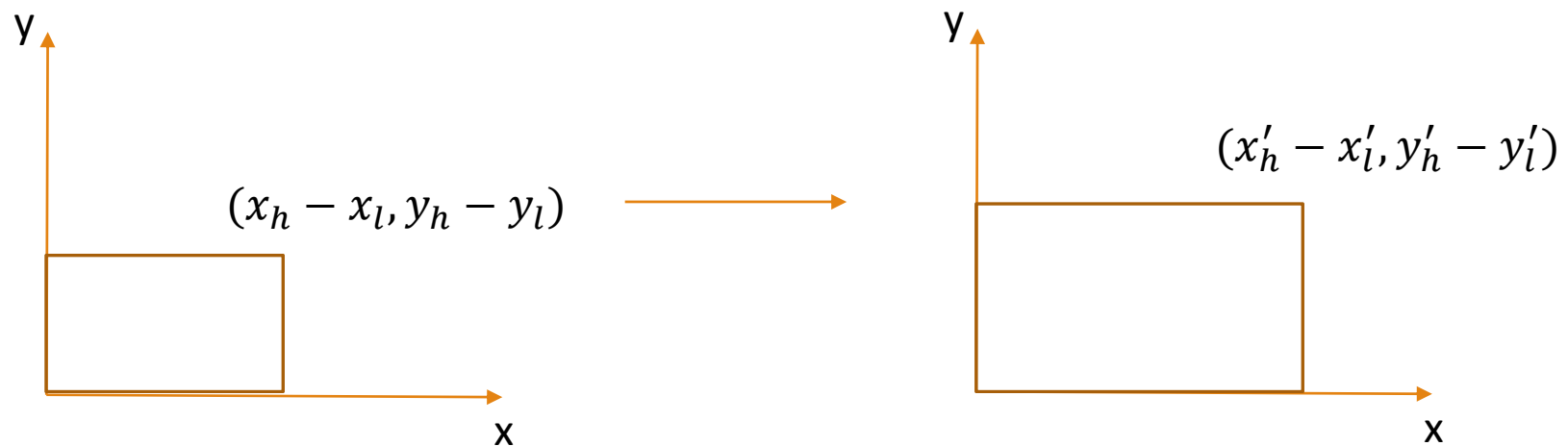
Example: Windowing Transform

- Problem specification: move a 2D rectangle into a new position
 - Step1. translate: move the point (x_l, y_l) to the origin



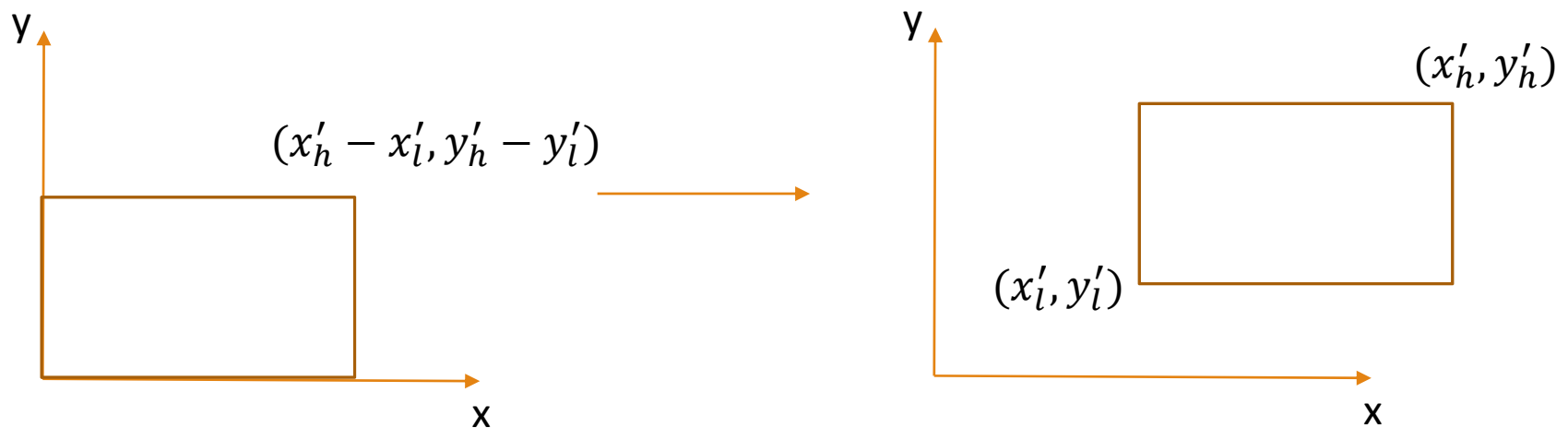
Example: Windowing Transform

- Problem specification: move a 2D rectangle into a new position
 - Step2. scale: resize the rectangle to be the same size of the target.



Example: Windowing Transform

- Problem specification: move a 2D rectangle into a new position
 - Step3. translate: move the origin to point (x'_i, y'_i)



Example: Windowing Transform

- Problem specification: move a 2D rectangle into a new position
 - Target = $\text{translate}(x'_l, y'_l) \text{ scale} \left(\frac{x'_h - x'_l}{x_h - x_l}, \frac{y'_h - y'_l}{y_h - y_l} \right) \text{ translate}(-x_l, -y_l)$

- $$= \begin{bmatrix} 1 & 0 & x'_l \\ 0 & 1 & y'_l \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{x'_h - x'_l}{x_h - x_l} & 0 & 0 \\ 0 & \frac{y'_h - y'_l}{y_h - y_l} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -x_l \\ 0 & 1 & -y_l \\ 0 & 0 & 1 \end{bmatrix}$$

- $$= \begin{bmatrix} \frac{x'_h - x'_l}{x_h - x_l} & 0 & \frac{x'_l x_h - x'_h x_l}{x_h - x_l} \\ 0 & \frac{y'_h - y'_l}{y_h - y_l} & \frac{y'_l y_h - y'_h y_l}{y_h - y_l} \\ 0 & 0 & 1 \end{bmatrix}$$

Viewport Transformation

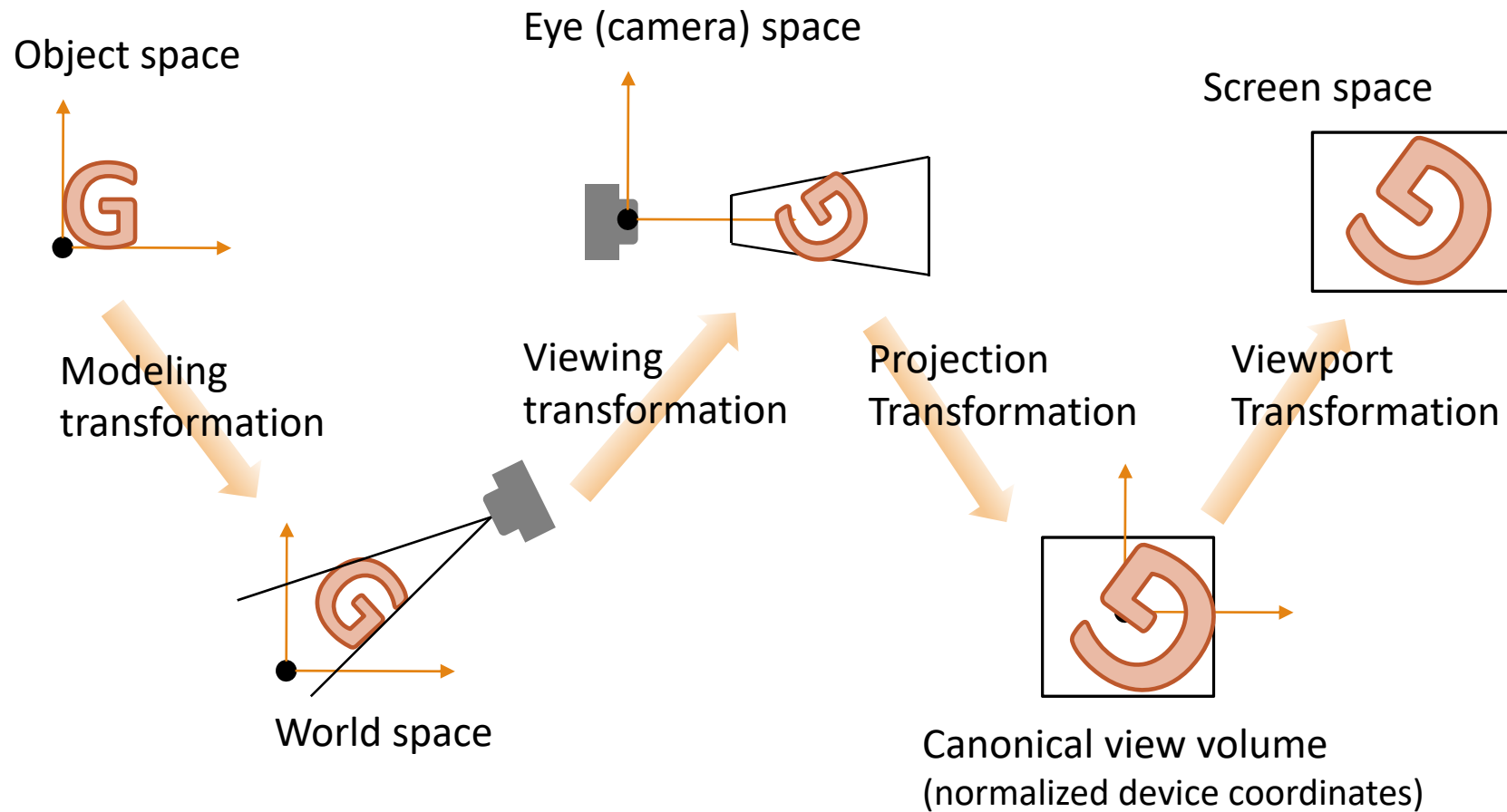
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- $$\begin{bmatrix} x_{screen} \\ y_{screen} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{n_x}{2} & 0 & \frac{n_x-1}{2} \\ 0 & \frac{n_y}{2} & \frac{n_y-1}{2} \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_{canonical} \\ y_{canonical} \\ 1 \end{bmatrix}$$

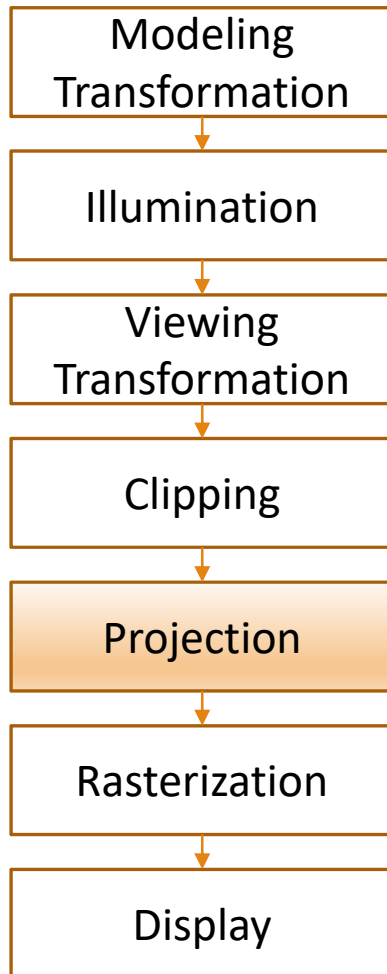
- For the case with z-coordinates,

- $$M_{viewport} = \begin{bmatrix} \frac{n_x}{2} & 0 & 0 & \frac{n_x-1}{2} \\ 0 & \frac{n_y}{2} & 0 & \frac{n_y-1}{2} \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

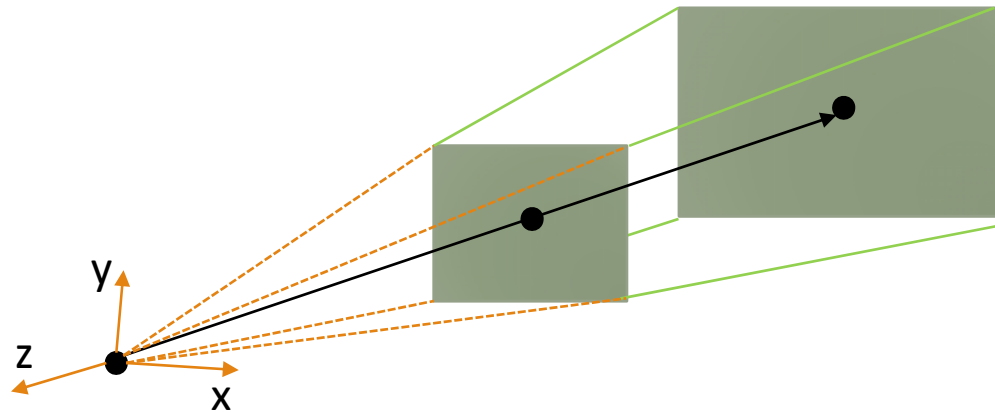
Sequence of Spaces and Transformations



Projections



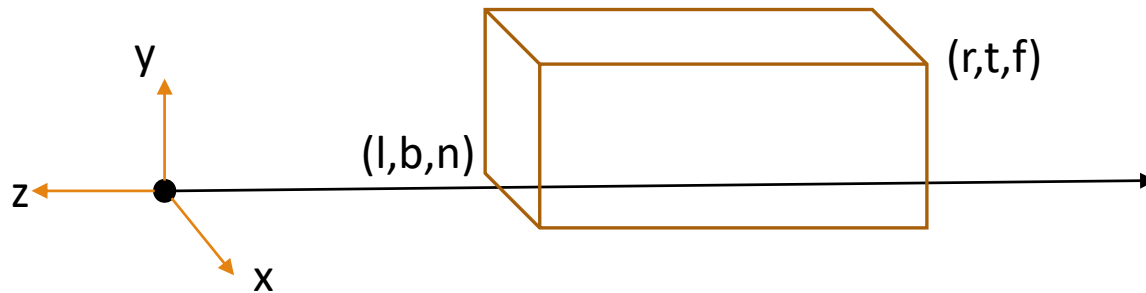
- Transform 3D points in *eye space* to 2D points in *image space*



- Two types of projections
 - Orthographic projection
 - Perspective projection

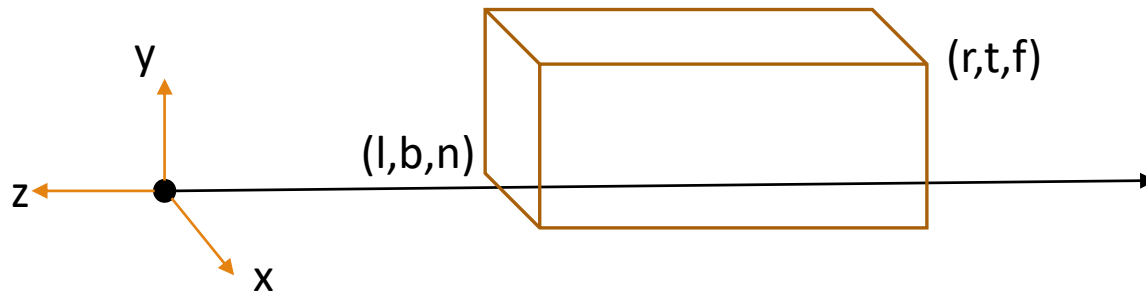
Orthographic Projection

- Assumption
 - A viewer is looking along the minus z-axis with his head pointing in the y-direction
 - Implies $n > f$



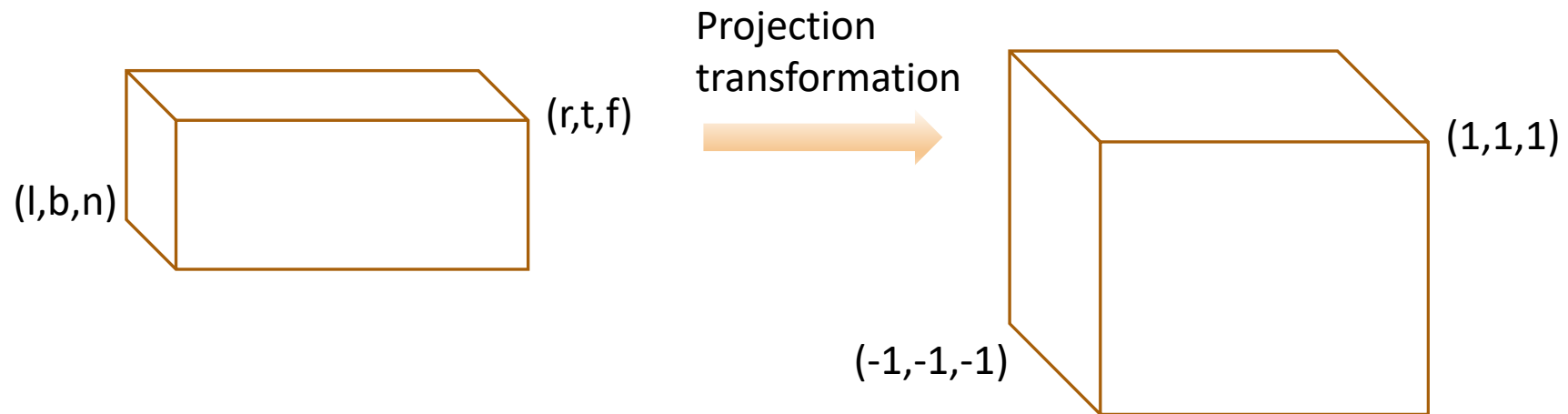
Orthographic Projection

- The view volume (*orthographic view volume*) is an axis-aligned box
 - $[l, r] \times [b, t] \times [f, n]$
- Notations
 - $x = l \equiv$ left plane, $x = r \equiv$ right plane
 - $y = b \equiv$ bottom plane, $y = t \equiv$ top plane
 - $z = n \equiv$ near plane, $z = f \equiv$ far plane



Orthographic Projection

- Transform points in orthographic view volume to the canonical view volume
 - Also windowing transform (3D)



Orthographic Projection

- Transform points in orthographic view volume to the canonical view volume
 - Also windowing transform (3D)
 - Map a box $[x_l, x_h] \times [y_l, y_h] \times [z_l, z_h]$ to another box $[x'_l, x'_h] \times [y'_l, y'_h] \times [z'_l, z'_h]$

$$\begin{bmatrix} \frac{x'_h - x'_l}{x_h - x_l} & 0 & 0 & \frac{x'_l x_h - x'_h x_l}{x_h - x_l} \\ 0 & \frac{y'_h - y'_l}{y_h - y_l} & 0 & \frac{y'_l y_h - y'_h y_l}{y_h - y_l} \\ 0 & 0 & \frac{z'_h - z'_l}{z_h - z_l} & \frac{z'_l z_h - z'_h z_l}{z_h - z_l} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Orthographic Projection

- Transform points in orthographic view volume to the canonical view volume
 - Also windowing transform (3D)

- $M_{ortho} = \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & \frac{2}{n-f} & -\frac{n+f}{n-f} \\ 0 & 0 & 0 & 1 \end{bmatrix}$

Composite Transformation

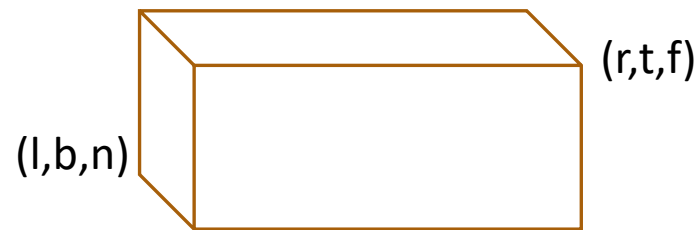
- The matrix that transforms points in world space to screen coordinate:
- $M = M_{viewport}M_{ortho}M_{viewing}$

Orthographic Projection

- Transform points in orthographic view volume to the canonical view volume
 - Also windowing transform (3D)
- Tend to ignore relative distances between objects and eye
 - Unrealistic
- In practice,
 - We usually do not use this projection.
 - It can be useful in applications where relative lengths should be judged.

Orthographic Projection in OpenGL

- `void glOrtho(GLdouble left, GLdouble right,`
- `GLdouble bottom, GLdouble top,`
- `GLdouble nearVal, GLdouble farVal);`



Perspective Projection

- Objects in an image become smaller as their distance from the eye increases.
- History of perspective:
 - Artists from the Renaissance period employed the perspective property.



Images from wikipedia

Perspective Projection

- Objects in an image become smaller as their distance from the eye increases.
- History of perspective:
 - Artists from the Renaissance period employed the perspective property.
- In everyday life?



Perspective Projection

- $y_s = \frac{d}{z} y$
 - y_s : y-axis coordinate in view plane
 - y : distance of the point along the y-axis

